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Statistical Analysis of a Risk Factor in Finance and Environmental Models for Belize

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Statistical Analysis of a Risk Factor in Finance and Environmental Models for Belize

by

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A dissertation submitted in partial fulfillment of the requirements for the degree of Doctor of Philosophy
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Abstract

The objectives of the study are to review and evaluate four basic risk models that are commonly used in investment science; statistically investigate the risk factor in Capital Asset Pricing Model (CAPM) that is used to reflect the safety of an investment decision in stocks; explore the statistical distribution of monthly precipitation in Belize and to forecast tourist arrivals using statistical time series modelling techniques. The risk models are the Capital Asset Pricing Model (Sharpe-Linter Version), Capital Asset Pricing Model (Conditional Version), Arbitrage Pricing Theory, and Fama–French three-factor model adopted in empirical investigations of asset pricing. The underlying assumptions of using these models are reviewed, and the statistical procedures to evaluate their robustness are reviewed.

It will be shown that the present manner of determining this risk factor is quite sensitive and misleading. We introduce a statistical procedure for obtaining a more robust measure of the risk factor commonly referred to as CAPM beta. Changes in the hydrological cycle will generate repercussions in all sectors. It is therefore imperative that Belize’s water resources be managed in an integrated manner, responding to the requirements of all sectors. Daily rainfall data have been collected for a period of 51 years (1960–2011) from The National Meteorological Service of Belize. The Wakeby distribution adequately fit the monthly rainfall data producing a suitable model based on the Kolmogorov–Smirnov test.
Tourism is vitally important to the entire Belize’s economy, contributing 50% of Belize's gross domestic product in 2015. It is the foremost foreign exchange earner in this small economy, followed by exports of marine products, citrus, cane sugar, bananas, and garments. The tourist sector is not without its vulnerabilities and is subject to international economic vagaries. In order to meet the expected future demands on the industry in terms of service delivery it is important that the sector understands the significance of forecasting.
Chapter 1: Importance of the Present Studies; A Review

This chapter introduces the remainder of the dissertation thesis. We will be presenting its most basics features, make essential connections between different methodologies that are put into use, and finally discuss the structure of the manuscript.

Introduction

We encounter risks in everything we do, be it, in health, investment, insurance, politics and defense. The term risk itself is very difficult to pin down precisely. It evokes notions of uncertainty, randomness, and probability according to Dowd (2005). The random outcome to which it alludes might be good or bad and we may or may not prefer to focus on the risks associated with bad events, presumably with a view to try to protect ourselves against them. Concentrating on the investment aspect, when a portfolio manager gives you a risk value in making a recommendation, the question that should arise is how good is that value in decision making? Our finding, is that, the risk is as good as the assumptions their making in the calculation that convey the risk. This study’s objective is to concentrate on a particular risk model that we can improved on, to avoid the misleading interpretations and in order to do that, we identified all the popular models and then we want to dig into these models to see if the manner in which the risk value is obtain is correct or misleading. It turns out from our results that some of the risk models are misleading. Before we proceed, a sound understanding of what risk is and how it is measured is vital. Hence, the first part of chapter 2 is a review of the most popular models.
The notion of risk in its broadest sense therefore has many facets, and there is no single definition of risk that can be completely satisfactory in every situation (Dowd 2007). However, for our purpose here, a reasonable definition is to consider it as the likelihood that we will receive a return on an investment that is different from the return we expected to make.

The normality factor is of concern to us, because to assume normality in the returns implies symmetry and there is no symmetry in returns. In fact, there is skewness to the left or right. By making a normal symmetry, the assumption will give a risk factor that is misleading. The quadratic aspect we are questioning is whether it is the best mathematical characterization or there should be another one? These are the two aspects we are concern with and we are investigating them further.

Chapter 3 focuses on the measure of risk that is commonly used in investment namely CAPM and investigates the underlying assumptions. Historically, most investors included as part of their management strategy a risk measure that is based on historical factors. The common risk measure is the risk associated with the Capital Asset Pricing Model. The CAPM model however is driven by a set of assumptions; one of which is the normality assumption of the returns. Natural phenomena often produce departures from normality and many recent findings suggest that the most commonly used estimation methods exhibit varying degrees of non-robustness to certain violations of the assumption of normality. In practice, it is not customary to get normal data in many real-world applications, researchers are uncertain about the true nature of the distribution of the errors and a naïve application of the normal distribution can give the user the wrong impression that he or she has obtained a useful inferential result. This can lead to misleading information later being passed on to financial advisors and later to their clients with regards to investment options. Chapter 3 continues with the introduction of a statistical
procedure for obtaining a more robust measure of risk premium beta. This process included the 
best justification of the selection process of the probability distribution that drives the estimate of 
the CAPM beta. Our research findings indicated that the distribution of beta is not normal but 
rather a Johnson 4p probability distribution.

The influence of rainfall on water quality, agriculture and tourism among others cannot 
be over emphasized. Because agriculture and tourism are the largest income earners for Belize, it 
is vital that we understand our rainfall system and possess the ability to model and forecast the 
rainfall, this gives added value to any major investment or planning. In Chapter 4, we focus on 
the parametric statistical analysis of Belize’s rainfall. The primary goal of this chapter is to 
analyze actual precipitation data collected in fifteen meteorological stations in Belize. There are 
other stations but because of data length, we chose only fifteen. We first identify the probability 
density function (PDF) that best characterizes the behavior, the Wakeby distribution for the 
entire data and then separated the data by the two seasons in Belize namely the wet and dry 
season. We conducted a hypothesis testing to determine if there is a distinction between the two 
seasons. We then transformed the data using a Box Cox transformation and then do a cluster 
analysis on the 15 weather stations.

The determination of the best fit distribution to represent the rainfall process in stations of 
Belize is discussed in this paper. An extensive search comparing several distribution such as 
Wakeby, lognormal, gamma, Weibull, Generalized Pareto, Dugan and many other distributions 
have been used on the monthly average rainfall data from 1960 to 2011. The selection of the 
best fit distribution is done by examining the minimum error produced by the Kolmogorov 
Smirnov (KS) goodness of fit test. Based on the results of KS goodness of fit test, Wakeby
distribution is the most suitable to describe the rainfall patterns in the stations of Belize as the error produced is the minimum.

In Chapter 5, we did times series analysis on Belize’s tourist arrival data with the objective of identifying the best forecasting model. First we test the data for stationarity, meaning that the mean and variance does not change over time and that the process does not have a trend. The two forecasting procedures that we utilize are the Holt-Winters exponential smoothing and Seasonal ARIMA model. Both of these models appear to fit the data well. In further analysis of the residuals, we conclude that the Holt Winter is the optimal forecasting model based on the data used in the study. Although our data set was specific, the same methodology can be applied to similar time series data.

Exponential smoothing and ARIMA models are the two most widely-used approaches to time series forecasting, and provide complementary approaches to the problem. While exponential smoothing models were based on a description of trend and seasonality in the data, ARIMA models aim to describe the autocorrelations in the data.

The dissertation concludes with Chapter 6, where possible future directions are explained along with future consideration with regards to the work already presented.
Chapter 2: Risk Analysis for Investment

Introduction

Risk is a part of investing and a sound understanding of what risk is and how it is measured is vital to investment. We start our discussion by defining risk. Webster's dictionary defines risk as “exposing to danger or hazard”. Thus, risk is perceived, by Webster, almost entirely in negative terms. In finance, our definition of risk is both different and broader. Risk, as we see it, refers to the likelihood that we will receive a return on an investment that is different from the return we expected to make. Thus, risk includes not only the bad outcomes, i.e., returns that are lower than expected, but also good outcomes, i.e., returns that are higher than expected. In fact, we can refer to the former as downside risk and the latter is upside risk; and we consider both when measuring risk.

The foundations for the development of asset pricing models were laid by Markowitz (1952) and Tobin (1958). Early theories suggested that the risk of an individual security is the standard deviation of its returns – a measure of return volatility. Thus, the larger the standard deviation of security returns, the greater the risk. An investor’s main concern, however, is the risk of his/her total wealth made up of a collection of securities, the portfolio. Markowitz (1952) observed that (i) when two risky assets are combined, their standard deviations are additive only in the case that the two assets are perfectly positively correlated and (ii) when a portfolio of risky assets is formed, the standard deviation risk of the portfolio is less than the sum of the standard deviations of its constituents. Markowitz was the first to develop a specific measure of portfolio risk and to derive the expected return and risk of a portfolio. The Markowitz model generates the
efficient frontier of portfolios and the investors are expected to select a portfolio, which is most appropriate for them, from the efficient set of portfolios made available. Tobin (1958) suggested a course of action to identify the appropriate portfolios among the efficient set. The computation of risk reduction as proposed by Markowitz is tedious. Sharpe (1964) developed a computationally efficient method, the single index model, where the return on an individual security is related to the return on a common index. The common index may be any variable thought to be the dominant influence on stock returns and need not be a stock index (Jones, 1991). The single index model can be extended to portfolios as well. This is possible because the expected return on a portfolio is a weighted average of the expected returns on individual securities.

When analyzing the risk of an individual security; however, the individual security risk must be considered in relation to other securities in the portfolio. In particular, the risk of an individual security must be measured in terms of the extent to which it adds risk to the investor’s portfolio. Thus, a security’s contribution to the portfolio risk is different from the risk of the individual security. Investors face two kinds of risks, namely, diversifiable (unsystematic) and non-diversifiable (systematic). Unsystematic risk is the component of the portfolio risk that can be eliminated by increasing the portfolio size, the reason being that risks that are specific to an individual security such as business or financial risk can be eliminated by constructing a well-diversified portfolio. Systematic risk is associated with overall movements in the general market or economy and therefore is often referred to as the market risk. The market risk is the component of the total risk that cannot be eliminated through portfolio diversification.
The main objective of this chapter is to review the conceptual idea behind asset pricing models and to discuss the testing and evaluation methods. This chapter is organized as follows. Section 2 discusses the four commonly used risk models. These risk models are the Capital Asset Pricing Model (Sharpe-Linter Version), Capital Asset Pricing Model (Conditional Version), Arbitrage Pricing Theory and a Multifactor model adopted in empirical investigations of asset pricing. Section 3 discusses the empirical findings regarding the four models. The final section concludes the chapter. In what follow we shall address very popular investment strategies. Relevant information on the mission of the present study can be found in Fama and French (1996), Fama and French (1996), Connor and Sehgal (2001), Chawarit (1996), Chanthirakul (1998), Fama and French (1992), Ross (1976), Sharpe (1964), Lintner (1965), Mossin (1966), Brigham and Ehrhardt (2005).

A Review of Current Risk Models

In what follows, we shall address commonly used risk models, the Capital Asset Pricing Model (Sharpe-Linter Version), Capital Asset Pricing Model (Conditional Version), Arbitrage Pricing Theory and a Multifactor model which are very popular in investment strategies.

The Capital Asset Pricing Model (CAPM)

Investors who buy assets expect to earn returns over the time horizon that they hold the asset. Their actual returns over this holding period may be very different from the expected returns and it is this difference between actual and expected returns that is source of risk. The risk and return model that has been in use the longest and is still the standard in most real world analyses is the capital asset pricing model (CAPM). The CAPM conveys the notion that securities are priced so that the expected returns will compensate investors for the expected risks.
There are two fundamental relationships: the capital market line (CML) and the security market line (SML). These two models are the building blocks for deriving the CAPM.

The CML specifies the return an individual investor expects to receive on a portfolio. This is a linear relationship between risk and return on efficient portfolios that can be written as:

$$E(R_p) = r_f + \sigma_p \left( \frac{E(R_m) - r_f}{\sigma_m} \right)$$

(2.1)

where $R_p$ is portfolio return, $r_f$ risk-free asset return, $R_m$ market portfolio return, $\sigma_p$ and standard deviation of portfolio returns and $\sigma_m$ is standard deviation of market portfolio returns.

According to Equation 2.1, the expected return on a portfolio can be thought of as the sum of the return for delaying consumption and a premium for bearing the risk inherent in the portfolio. The CML is valid only for efficient portfolios and expresses investors’ behavior regarding the market portfolio and their own investment portfolios.

The Security market line (SML) expresses the return an individual investor can expect in terms of a risk-free rate and the relative risk of a security or portfolio. The SML with respect to security $i$ can be written as:

$$E(R_i) = r_f + \beta_{im} (E(R_m) - r_f)$$

(2-2)

where
\[ \beta_{im} = \frac{\sigma_{im}}{\sigma_m^2} = \frac{\text{cov}(R_i, R_m)}{\sigma_m^2} \] (2-3)

and \( \sigma_{im} \) the covariance between security return, \( R_i \), and market portfolio return. The \( \beta_{im} \) can be interpreted as the amount of non-diversifiable risk inherent in the security relative to the risk of the market portfolio. Equation (2.2) is the Sharpe–Lintner version of the CAPM. The set of assumptions sufficient to derive the CAPM version of (Equation 2.2) are the following:

- the investor’s utility functions are either quadratic or normal,
- all diversifiable risks are eliminated, and
- the market portfolio and the risk-free asset dominate the opportunity set of risky assets.

The SML is applicable to portfolios as well. Therefore, SML can be used in portfolio analysis to test whether securities are fairly priced, or not.

The three assumptions above can be further broken down into eight assumptions for the CAPM, namely:

1. Investors are rational and risk averse. They pursue single-mindedly the maximization of the expected utility of their end of period wealth. Implication: The model includes the single time horizon for all investors.
2. The markets are perfect, thus taxes, inflation, transaction costs, and short selling restrictions are not taken into account.
3. Investors can borrow and lend unlimited amounts at the risk-free rate.
4. All assets are infinitely divisible and perfectly liquid.
5. Investors have homogenous expectations about asset returns. In other words, all investors agree about mean and variance as the only system of market assessment, thus
everyone perceives identical opportunity. The information is costless, and all investors receive the same information simultaneously.

6. Asset returns conform to the normal distribution.

7. The markets are in equilibrium, and no individual can affect the price of a security.

8. The total number of assets on the market and their quantities are fixed within the defined time frame.

Once you accept the assumptions that lead to all investors holding the market portfolio and measure the risk of an asset with beta, the return you can expect to make can be written as a function of the risk-free rate and the beta of that asset. Table 2-1 outlines some advantages and disadvantages of using CAPM.

**Conditional CAPM**

One of the commonly made assumptions is that the betas of the assets remain constant over time. However, this is not a particularly reasonable assumption since the relative risk of a firm's cash flow is likely to vary over the business cycle. Hence, betas and expected returns will in general depend on the nature of the information available at any given point in time and vary over time. Ravi Jagannathan and Zhenyu Wang (1996) assumed that the expected return on an asset based on the information available at any given point in time is linear in its conditional beta, and introduced the idea of the Conditional CAPM.

We use the subscript \( t \) to indicate the relevant time period. For example, \( R_{it} \) denotes the gross (one plus the rate of) return on asset \( i \) in period \( t \), and \( R_{mt} \), the gross return on the aggregate wealth portfolio of all assets in the economy in period \( t \). We refer to \( R_{mt} \), as the market return. Let \( I_{t-1} \) denote the common information set of the investors at the end of period \( t - 1 \). In this paper
Table 2.1: Advantages and disadvantages of CAPM

<table>
<thead>
<tr>
<th>Advantages of CAPM</th>
<th>Disadvantages of CAPM</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Market portfolio includes all the risky assets including human capital while the proxy just contains the subset of all assets</td>
<td>1. Inability to observe the true market portfolio</td>
</tr>
<tr>
<td>2. It has given a measure of risk, market beta, interpreted as market sensitivity</td>
<td>2. Liable to Type I and Type II errors</td>
</tr>
<tr>
<td>3. The popularity and attractiveness of CAPM is its potential testability</td>
<td>3. In order to use the CAPM, values need to be assigned to the risk-free rate of return, the return on the market, or the equity risk premium (ERP), and the equity beta.</td>
</tr>
<tr>
<td>4. If empirically true, it has a wide ranging implication in capital budgeting, cost benefit analysis, portfolio selection and development of investment strategies</td>
<td>4. The yield on short-term Government debt, which is used as a substitute for the risk-free rate of return, is not fixed but changes on a daily basis according to economic circumstances. A short-term average value can be used in order to smooth out this volatility.</td>
</tr>
<tr>
<td>5. CAPM durability is due to the fact that it explains return common variability in terms of a single factor, which generates return for each individual asset via some linear functional relationship</td>
<td>5. Finding a value for the ERP is more difficult.</td>
</tr>
<tr>
<td>6. It considers only systematic risk, reflecting a reality in which most investors have diversified portfolios from which unsystematic risk has been essentially eliminated</td>
<td>6. Beta values are now calculated and published regularly for all stock exchange-listed companies. The problem here is that uncertainty arises in the value of the expected return because the value of beta is not constant, but changes over time.</td>
</tr>
<tr>
<td>7. It generates a theoretically-derived relationship between required return and systematic risk which has been subject to frequent empirical research and testing</td>
<td>7. One disadvantage in using the CAPM in investment appraisal is that the assumption of a single-period time horizon is at odds with the multi-period nature of investment appraisal. While CAPM variables can be assumed constant in successive future periods, experience indicates that this is not true in reality.</td>
</tr>
<tr>
<td>8. It is generally seen as a much better method of calculating the cost of equity than the dividend growth model (DGM) in that it explicitly takes into account a company’s level of systematic risk relative to the stock market as a whole.</td>
<td></td>
</tr>
<tr>
<td>9. It is clearly superior to the WACC in providing discount rates for use in investment appraisal.</td>
<td></td>
</tr>
</tbody>
</table>
we assume all the time series in this paper are covariance stationary and all the conditional and unconditional moments that we use exist.

Risk-averse rational investors living in a dynamic economy will typically anticipate and hedge against the possibility that investment opportunities in the future may change adversely. Because of this hedging need that arises in a dynamic economy, the conditionally expected return on an asset will typically be jointly linear in the conditional market beta and hedge portfolio beta. However, employing Merton (1980) findings, we will assume that the hedging motives are not sufficiently important, and hence the CAPM will hold in a conditional sense as given below.

For each asset $i$ and in each period $t$,

$$E(R_i|I_{t-1}) = \gamma_0t^{-1} + \gamma_1t^{-1} \beta_{it-1}$$  \hspace{1cm} (2.4)

Where $\beta_{it-1}$ is the conditional beta of asset $i$ defined as,

$$\beta_{it-1} = \frac{cov(R_{it}, R_{mt}|I_{t-1})}{Var(R_{mt}|I_{t-1})}$$  \hspace{1cm} (2.5)

$\gamma_{0t-1}$, is the conditional expected return on a "zero-beta" portfolio, and $\gamma_{1t-1}$, is the conditional market risk premium.

Since our aim is to explain the cross-sectional variations in the unconditional expected return on different assets, we take the unconditional expectation of both sides of equation (2) to get

$$E(R_{it}) = \gamma_0 + \gamma_1 \bar{\beta}_i + cov(\gamma_{1t-1}, \beta_{it-1})$$  \hspace{1cm} (2.6)

where
\[
\gamma_0 = E(\gamma_{0t-1}) \quad \gamma_1 = E(\gamma_{1t-1}) \quad \text{and} \quad \tilde{\beta}_i = E(\beta_{it-1}).
\]

Here, \(\gamma_1\) is the expected market risk premium, and \(\tilde{\beta}_i\) is the expected beta. If the covariance between the conditional beta of asset \(i\) and the conditional market risk premium is zero (or a linear function of the expected beta) for every arbitrarily chosen asset \(i\), then equation (4) resembles the static CAPM, i.e., the expected return is a linear function of the expected beta.

Jagannathan and Wang (1996) argued that the two assumptions of Fama and French (1992) are not reasonable. Relaxing the first assumption naturally leads them to examine the conditional CAPM. They demonstrated that the empirical support for the conditional CAPM specification is rather strong. When betas and expected returns are allowed to vary over time by assuming that the CAPM holds period by period, the size effects and the statistical rejections of the model specifications become much weaker. When a proxy for the return on human capital is also included in measuring the return on aggregate wealth, the pricing errors of the model are not significant at conventional levels. More importantly, firm size does not have any additional explanatory power.

The conditional CAPM is very different from what is commonly understood as the CAPM, and resembles the multi-factor model of Ross (1976). The model evaluated has three betas, whereas the standard CAPM has only one beta. Jagannathan and Wang (1996) chose this model because (i) the use of a better proxy for the return on the market portfolio results in a two-beta model in place of the classical one-beta model, and (ii) when the CAPM holds in a conditional sense, unconditional expected returns will be linear in the unconditional beta as well as a measure of beta-in instability over time. When the CAPM holds conditionally, we need more than the unconditional beta calculated by using the value-weighted stock index to explain the cross-section of unconditional expected returns.

**Arbitrage Pricing Theory**

The Arbitrage Pricing Theory (APT) is a very detailed pricing method. The APT is based on five different economic factors. The factors are: business cycle, time horizon, confidence, inflation and market timing risk. The advantage of using the APT in portfolio selection and portfolio risk management is that the model makes the fundamental sources of risk explicit. In this method these factors are related to the expected return of risky investments. By using these macroeconomic variables it provides a way to estimate the risk premium for every individual variable. Why is that important to an investor? For some investors some risk criteria or variables are more important than others.

To understand the arbitrage pricing model, we need to begin with a definition of arbitrage. The basic idea is a simple one. Two portfolios or assets with the same exposure to market risk
should be priced to earn exactly the same expected returns. If they are not, you could buy the less expensive portfolio, sell the more expensive portfolio, have no risk exposure and earn a return that exceeds the riskless rate. This is arbitrage. If you assume that arbitrage is not possible and that investors are diversified, you can show that the expected return on an investment should be a function of its exposure to market risk. While this statement mirrors what was stated in the capital asset pricing model, the arbitrage pricing model does not make the restrictive assumptions about transactions costs and private information that lead to the conclusion that one beta can capture an investment’s entire exposure to market risk. Instead, in the arbitrage pricing model, you can have multiples sources of market risk and different exposures to each (betas). The model assumes that the return to the $i^{th}$ security, $R_{it}$, is generated by a multi-index model:

$$R_{it} = a_i + \beta_{i1}(F_{1t}) + \cdots + \beta_{iJ}(F_{Jt}) + \varepsilon_{it}; \quad i = 1,2, \ldots N,$$

(2.7)

Where the $F_{jt}$ are factors ($j=1,2,\ldots,J$); the $\beta_{ij}$ are factor loading or sensitivities and $\varepsilon_i$ is a random variable with $E(\varepsilon_i)=0$, $E(\varepsilon_i^2)=\sigma_i^2$, $E(\varepsilon_i\varepsilon_k)=0$ for $i \neq j$ and $cov(\varepsilon_i,F_j)=0$ for all $i$ and $j$.

The focus of the APT is on the expected return $E(R_{it})$. Assuming:

1. There are no arbitrage possibilities

2. The law of large number,

the model implies the following relationship between the expected return to asset and the factor loadings(sensitivities)

$$E(R_{it}) = \alpha_0 + \alpha_1 b_{i1} + \cdots + \alpha_J b_{ij} + \varepsilon_{it}$$

(2.8)

Where $\alpha_0$ usually equals the risk-free rate of return and $\alpha_j$ has the interpretation of the expected return to a portfolio (risk price) with unit sensitivity to factor $j$ and zero sensitivity to all other factors.
The practical questions then become knowing how many factors there are that determine expected returns and what the betas for each investment are against these factors. The arbitrage model estimates both by examining historical data on stock returns for common patterns (since market risk affects most stocks) and estimating each stock’s exposure to these patterns in a process called factor analysis. A factor analysis provides two output measures:

1. It specifies the number of common factors that affected the historical return data
2. It measures the beta of each investment relative to each of the common factors and provides an estimate of the actual risk premium earned by each factor.

The factor analysis does not, however, identify the factors in economic terms – the factors remain factor 1, factor 2 etc. In summary, in the arbitrage pricing model, the market risk is measured relative to multiple unspecified macroeconomic variables, with the sensitivity of the investment relative to each factor being measured by a beta. The number of factors, the factor betas and factor risk premiums can all be estimated using the factor analysis. Table 2.1 outlines some advantages and disadvantages of APT.

**Fama–French Three-Factor Model**

The Factor Model expands on the capital asset pricing model (CAPM) by adding size and value factors in addition to the market risk factor in CAPM. This model considers the fact that value and small cap stocks outperform markets on a regular basis. By including these two additional factors, the model adjusts for the outperformance tendency, which is thought to make it a better tool for evaluating manager performance.
Table 2.2: Advantages and Disadvantages of APT

<table>
<thead>
<tr>
<th>Advantages of APT</th>
<th>Disadvantages of APT</th>
</tr>
</thead>
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<tr>
<td>1. Underlying assumption is that the return generating process is stationary</td>
<td>1. The number of institutional investors actually using APT is small</td>
</tr>
<tr>
<td>2. APT operates under relative weaker assumptions</td>
<td>2. The arbitrage pricing model's failure to identify the factors specifically in the model may be a statistical strength, but it is an intuitive weakness</td>
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<tr>
<td>3. Emphasis on multiple systematic risk</td>
<td>3. Even professionals and academics can't agree on the identity of the risk factors, and the more betas you have to estimate, the more statistical noise you must live with.</td>
</tr>
<tr>
<td>4. It appears to better explain investment results and more efficiently controls portfolio risks</td>
<td></td>
</tr>
<tr>
<td>5. APT models allow for priced factors that are orthogonal to the market return and do not require that all investors are mean–variance optimizers, as in the CAPM</td>
<td></td>
</tr>
<tr>
<td>6. The APT demands that investors perceive the risk sources, and that they can reasonably estimate factor sensitivities.</td>
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Previous work shows that average returns on common stocks are related to firm characteristics like size, earnings/price, cash flow/price, book-to-market equity, past sales growth, long-term past return, and short-term past return. Because these patterns in average returns apparently are not explained by the CAPM, they are called anomalies. Eugene Fama and Kenneth French find that, except for the continuation of short-term returns, the anomalies largely disappear in a three-factor model. Their results are consistent with rational ICAPM or APT.

CAPM uses a single factor, beta, to compare the excess returns of a portfolio with the excess returns of the market as a whole. But it oversimplifies the complex market. Fama and French started with the observation that two classes of stocks have tended to do better than the market as a whole: (i) small caps and (ii) stocks with a high book-to-market ratio (BM, customarily called
value stocks, and different from growth stocks). They then added two factors to CAPM to reflect a portfolio's exposure to these two classes:

\[
E(r_p) = r_f + \beta_{t,m}(E(r_m) - r_f) + \beta_{t,SMB}(SMB) + \beta_{t,HML}(HML) + \epsilon_p
\]  

(2-9)

Here \(r_p\) is the portfolio's rate of return, \(r_f\) is the risk-free return rate, and \(r_m\) is the return of the whole stock market. The "three factor" \(\beta\) is analogous to the classical \(\beta\) but not equal to it, since there are now two additional factors to do some of the work. \(SMB\) stands for "small (market capitalization) minus big" and \(HML\) for "high (book-to-price ratio) minus low"; they measure the historic excess returns of small caps over big caps and of value stocks over growth stocks. These factors are calculated with combinations of portfolios composed by ranked stocks and available historical market data.

Fama and French (1993) find that the three-factor risk-return relation is a good model for the returns on portfolios formed on size and book-to-market equity. They found that the three factor model also explains the strong patterns in returns observed when portfolios are formed on earnings/price, cash flow/price, and sales growth, variables recommended by Lakonishok, Shleifer, and Vishny (1994) and others. The three-factor risk-return relation also captures the reversal of long-term returns documented by DeBondt and Thaler (1985). Thus, portfolios formed on E/P, C/P, sales growth, and long-term past returns do not uncover dimensions of risk and expected return beyond those required to explain the returns on portfolios formed on size and BE/ME. Fama and French (1994) extend their conclusion to industries. The three-factor risk-return relation (Equation 2.9) is, however, just a model. It surely does not explain expected returns on all securities and portfolios. We find that (1) cannot explain the continuation of short-term returns documented by Jegadeesh and Titman (1993) and Asness (1994).
Empirical Testing

The current approaches of testing and calculating the risk factor on investment returns are sensitive to the assumption of the symmetry. The accuracy and robustness of the models in discussed above is still yet to be answered. As part of the review process we examined the different methods in which the models of interest are tested.

Testing CAPM

Another possible problem in many early tests of CAPM has arisen due to it being a single period model. Most tests have used time series regression, which is appropriate, if the risk premia and betas are stationary, which is unlikely to be true. Several researches have focused on the validity of CAPM and the findings from earlier to even more recent ones appear to be mixed. In order to test the validity of the CAPM researchers, always test the SML given in (Equation 2.10). The CAPM is a single-period ex-ante model. However, since the ex-ante returns are unobservable, researchers rely on realized returns. So the empirical question arises: Do the past security returns conform to the CAPM? The beta in such an investigation is usually obtained by estimating the security characteristic line (SCL) that relates the excess return on security i to the excess return on some efficient market index at time t. The ex post SCL can be written as:

\[ R_{it} - r_{ft} = \alpha_i + b_{im} (R_{mt} - r_{ft}) + \epsilon_{it} \]  

(2.10)

where \( \alpha_i \) is the constant return earned in each period and \( b_{im} \) is an estimate of \( \beta_{im} \) in the SML (Jensen, 1968). The estimated \( \beta_{im} \) is then used as the explanatory variable in the following cross-sectional equation:
\[ R_{it} - r_{ft} = \gamma_0 + \gamma_1 b_{im} + \delta_{it} \]  

(2.11)

to test for a positive risk return trade-off. The coefficient \( \gamma_0 \) is the expected return of a zero beta portfolios, expected to be the same as the risk-free rate, and \( \gamma_1 \) is the market price of risk (market risk premium), which is significantly different from zero and positive in order to support the validity of the CAPM. When testing the CAPM using (4) and (5), we are actually testing the following issues: (i) \( b_{im} \)'s are true estimates of historical \( \beta_{im} \)'s, (ii) the market portfolio used in empirical studies is the appropriate proxy for the efficient market portfolio for measuring historical risk premium and lastly whether the CAPM specifications are correct. Other methodology have been used for estimating the market model like Lagrange Multiplier, Maximum likelihood ratio test and Hotelling T\(^2\) statistics, they all reject CAPM.

The mixed empirical findings on the return–beta relationship prompted a number of responses:

- The single-factor CAPM is rejected when the portfolio used as a market proxy is inefficient (See [2], for example, Roll, 1977; Ross, 1977). Even very small deviations from efficiency can produce an insignificant relationship between risks and expected returns (Roll and Ross, 1994; Kandel and Stambaugh, 1995).

- Kothari et al. (1995) highlighted the survivorship bias in the data used to test the validity of the asset pricing model specifications.

- Beta is unstable over time (see, for example, Bos and Newbold, 1984); Faff et al., 1992; Brooks et al., 1994; Faff and Brooks, 1998).

- There are several model specification issues: For example, (i) Kim (1995) and Amihud et al. (1993) argued that errors-in-the-variables problem impact on the
empirical research. (ii) Kan and Zhang (1999) focused on a time-varying risk premium, (iii) Jagannathan and Wang (1996) showed that specifying a broader market portfolio can affect the results and (iv) Clare et al. (1998) argued that failing to take into account possible correlations between idiosyncratic returns may have an impact on the results.

**Testing Conditional CAPM**

The test of CCAPM becomes very difficult due to the problem of observing expected market return. To overcome the difficulties Tim Bollerslev (1988), Hall(1989) and Ng(1991) suggested to assume market price risk to be constant and hence requires a functional specification of variance and covariance structure. In earlier research works the presence of time varying moments in return distribution has been in the form of clustering large shocks of dependent variables and thereby exhibiting a large positive or negative value of the error term [Mandelbrot (1963) and Fama (1965)]. A formal specification was ultimately proposed by Engle (1982) in the form of Autoregressive Conditional Heteroscedastic (ARCH) process. Some of the latter studies have attempted to improve upon Engle’s ARCH specification [Engle and Bollerslev(1986)]. The approaches which are helpful in specifying functional form of error term in the test of CCAPM include the approaches given by Engle and Bollerslev (1986); Bollerslev et al. (1992) and Ng et al. (1992) in case of family of ARCH model.

The implicit assumption of Engle ARCH and Bollerslev GARCH is that return distribution characterized with time variation only in variance. But the evidence from various studies has shown time variation in both mean and variance of return distribution [Domowitz and Hakkins (1985)]. Incorporating this idea Engle (1987) has proposed the ARCH-M to account for time variation in both mean and variance
Lewellen and Nagel (2006) test the conditional CAPM by directly estimating conditional alphas and betas using short window regressions. That is, rather than estimate (Equation 2.2) once using the full times series of returns, they estimated it separately every, say, quarter using daily or weekly returns. The result is a direct estimate of each quarter's conditional alpha and beta; without using any state variables or making assumption about the quarter variation in beta.

**Testing APT**

The arbitrage pricing model's failure to identify the factors specifically in the model may be a statistical strength, but it is an intuitive weakness. The solution seems simple: Replace the unidentified statistical factors with specific economic factors and the resultant model should have an economic basis while still retaining much of the strength of the arbitrage pricing model. That is precisely what multifactor models try to do. Multi-factor models generally are determined by historical data, rather than economic modeling. Once the number of factors has been identified in the arbitrage pricing model, their behavior over time can be extracted from the data. The behavior of the unnamed factors over time can then be compared to the behavior of macroeconomic variables over that same period to see whether any of the variables are correlated, over time, with the identified factors.

A major problem in testing Arbitrage Pricing Theory is that the pervasive factors affecting asset returns are unobservable. The conventional factor extraction techniques are maximum likelihood factor analysis and principle component approach. Mostly factor analysis to measure these common factors has been used [Chen (1983); Roll and Ross (1980); Reinganum (1981); Lehmann and Modest (1988)]. While Connor and Korajczyk (1988) have used the asymptotic principal component technique to estimate the pervasive factors influencing asset returns and to test the restrictions imposed by static and intertemporal version of APT on a
multivariate regression model. The factor extraction analysis is only a statistical tool to uncover the pervasive forces (factors) in the economy by examining how asset returns covary together. In using maximum likelihood procedure, if one knows the factor loadings for say $k$ portfolio, then one can compute the $k$ factor loadings for all securities [Chen (1983)]. We can use factor analysis only on one group of securities or portfolios and the factor loadings of all securities will correspond to the same common factor. Since $b_{ik}$ (the sensitivity of asset $i$ to the $k^{th}$ factor) are not observable, we need to construct a proxy for the factor loadings. In factor analysis we can use estimated an $b$ as a proxy, then run a cross-sectional regression of $R_{it}$ on $b_{ik}$. We can use the autoregressive approach as well and derive the proxy from the return generating process. The intuition behind this is that historical excess returns are useful in explaining current cross sectional returns because they span the same return space as $b_{ik}$, and thus can be used as proxies for systematic risks. The substitution of excess return for unobservable $b_{ik}$ is similar in spirit to the technique of substituting mimicking factors portfolios return for unobservable factors used by Jobson (1982). After identifying the factor, we use the estimated factor loadings to explain the cross sectional variation of individual estimated expected returns and to measure the size and statistical significance of the estimated risk premia associated with each factor.

**Testing Fama–French Three-Factor Model**

Standard Multivariate Regression method is normally used to test Fama–French three-factor model (FF3FM hereafter). Once SMB and HML are defined in the model, the corresponding coefficients are determined by linear regressions and can take negative values as well as positive values. The FF3FM explains over 90% of the diversified portfolios returns, compared with the average 80% given by the CAPM. The signs of the coefficients suggested that
small cap and value portfolios have higher expected returns—and arguably higher expected risk—than those of large cap and growth portfolios.

The alternate approach in Chen, Roll and Ross (1986) is to look for economic variables that are correlated with stock returns and then to test whether the loading of these economic factors describe the cross section of expected returns. This approach thus gives insight about how the factors relate to uncertainties about consumption and portfolio opportunities that are of concern to investors.

**Conclusion**

The accuracy and robustness of the models in this research is still yet to be answered. Several researchers have tested the robustness of the results by using data from different market sources, for example, Japan, UK etc. However there is no consensus in the literature as to what is the suitable measure of risk.

The version of the CAPM by Sharpe and Lintner has never been an empirical success. More than a modest level of disappointment with the CAPM is evident by the number of related but different theories, for example, Hakanson (1971); Merton(1973); Ball (1978); Ross (1976); Reinganum (1981), and by the questioning of CAPM’s validity, as a scientific theory, e.g., Roll (1977, 1994). Nonetheless, the CAPM retains a central place in the thoughts of finance practitioners such as portfolio managers, investment advisors and security analysts. But there is a good reason for its durability, the fact that it explains return common variability in terms of a single factor, which generates return for each individual asset, via some linear functional relationship. The elegant derivation of CAPM is based on first principle of utility theory, and its continued attractiveness is due to its potential testability.
The important point to emphasize is that the Sharpe-Lintner-Black CAPM, Conditional CAPM, Consumption CAPM and the Multifactor Model are not mutually exclusive. Following Constantinides (1989), one can view the models as different ways of formulizing the asset pricing implications of common general assumptions about tastes (risk aversion) and portfolio opportunities (multivariate normality). Thus as long as major prediction of the models about the cross section of expected returns have some empirical content, and as long as we keep the empirical short comings of the models in mind, we have some freedom to lean on one model or another, to suit the purpose in hand.
Chapter 3: Proposed Analysis for Estimating Correctly the CAPM Beta

Introduction

Historically, most investors included as part of their management strategy a risk measure that is based on historical factors. The common risk measure is the risk associated with the Capital Asset Pricing Model (CAPM). The CAPM model however is driven by a set of assumptions; one of which is the normality assumption of the returns. Natural phenomena often produce departures from normality and many recent findings suggest that the most commonly used estimation methods exhibit varying degrees of non-robustness to certain violations of the assumption of normality. In practice, it is not customary to get normal data in many real-world applications, researchers are uncertain about the true nature of the distribution of the errors and a naïve application of the normal distribution can give the user the wrong impression that he or she has obtained a useful inferential result. This can lead to misleading information later being passed on to financial advisors and later to their clients with regards to investment options. We introduced a statistical procedure of obtaining a more robust measure of risk premium beta. This process included the best justification of the selection process of the probability distribution that drives the estimate of the CAPM beta.

If the correct PDF of the returns can be identified and implemented, in the estimation procedure, on the errors and the response, it is expected that this would improve the estimates and minimize the errors. We have indicated that most of the utility returns fit very well to a Johnson SU Distribution. In recent years, there has been increasing awareness that departure from gaussianity occurs and that the Gaussian distribution should be considered an exception rather than the rule in applied modeling work such as CAPM. In the meantime, there has been a
growing interest in the study of a flexible class of very rich distributional models that cover the Gaussian and other common distributions.

One practical approach to dealing with non-normality residual is the partially adaptive estimation, which fits a model selected from within a general parametric family of distributions to the error distribution of the data being analyzed. There must be a good reason for introducing a complex distribution, particularly if it requires more degrees of freedom than many distribution currently use. If the selected family includes the true error distribution as a special case then the corresponding estimator should perform similarly to MLE, allowing for some efficiency loss due to over-parameterization. This approach can be applied to CAPM where assumption of normality is the driving factor in the estimation of the parameter and the risk measure that investors use in their investment decision. The Johnson SU distributions have already been mentioned in some attempts to approximate the non-normal behavior of stock returns, but there is little information on the numerical efficiency of these models when applied to actual market data, or on its power to capture the effects of infrequent but largely negative returns which characterize the distributions of some hedge fund strategies.

The introduction of a not necessarily Normal probability density function to model the error of the CAPM parameter raises a number of questions such as:

1. Are estimates with the selected family of distribution routinely computable?
2. What practical differences does it make whether the error distribution is assumed to be normal or to belong to another family?
3. Does the new error model yield an advantage from the point of view of both fitting and efficiency?
4.
The Capital Asset Pricing Model (CAPM)

The capital asset pricing model is a theory based upon the theory of portfolio selection. The basic premise is that in capital markets people are rewarded for bearing risk. Any asset is priced in equilibrium so that if the asset is risky people receive a higher rate of return than they would receive if they held a risk free asset. This higher rate of return is called the risk premium. However, the market does not reward people for bearing unnecessary risk, risk that can be avoided by diversification.

The incremental impact on risk and expected return when an additional risky asset, \(i\), is added to the market portfolio, \(m\), follows from the formulae for a two-asset portfolio. These results are used to derive the asset-appropriate discount rate.

- Market portfolio's risk = \((\omega_m^2 \sigma_m^2 + [(\omega_i^2 \sigma_i^2 + 2\omega_m \omega_i \rho_{im} \sigma_i \sigma_m)])\)

  Hence, risk added to portfolio = \(\omega_i^2 \sigma_i^2 + 2\omega_m \omega_i \rho_{im} \sigma_i \sigma_m\)

  but since the weight of the asset will be relatively low, \(\omega_i^2 \approx 0\)

  therefore additional risk = \(2\omega_m \omega_i \rho_{im} \sigma_i \sigma_m\)

- Market portfolio's expected return = \(\omega_m E(R_m) + \omega_i E(R_i)\)

  Hence additional expected return = \(\omega_i E(R_i)\)

If an asset, \(i\), is correctly priced, the improvement in its risk-to-expected return ratio achieved by adding it to the market portfolio, \(m\), will at least match the gains of spending that money on an
increased stake in the market portfolio. The assumption is that the investor will purchase the asset with funds borrowed at the risk-free rate, \( R_f \), this is rational if \( E(R_i) > R_f \).

Thus:

\[
\frac{\omega_i (E(R_i) - R_f)}{2 \omega_m \omega_i \rho_{im} \sigma_i \sigma_m} = \frac{\omega_i (E(R_m) - R_f)}{2 \omega_m \omega_i \sigma_m \sigma_m}
\]

(3.1)

\[
E(R_{ai}) = R_f + (E(R_m) - R_f) \times \frac{\rho_{im} \sigma_i \sigma_m}{\sigma_m \sigma_m}
\]

(3.2)

\[
E(R_i) = R_f + (E(R_m) - R_f) \times \frac{\rho_{im}}{\sigma_{mm}}
\]

(3.3)

Where \( \frac{\rho_{im}}{\sigma_{mm}} \) is the "beta", \( \beta \) return— the covariance between the asset’s return and the market’s return divided by the variance of the market return— i.e. the sensitivity of the asset price to movement in the market portfolio’s value. Betas are standardized around one. If

\[ \beta = 1 \ldots \text{Average risk investment} \]

\[ \beta > 1 \ldots \text{Above Average risk investment} \]

\[ \beta < 1 \ldots \text{Below Average risk investment} \]

\[ \beta = 0 \ldots \text{Riskless investment} \]

The average beta across all investments is one.
The risk and return model that has been in use the longest and is still the standard in most real world analyses is the capital asset pricing model. Once you accept the assumptions that lead to all investors holding the market portfolio and measure the risk of an asset with beta, the return you can expect can be written as a function of the risk-free rate and the beta of that asset.

The asset return depends on the amount paid for the asset today. The price paid must ensure that the market portfolio’s risk (return) characteristics improve when the asset is added to it. The CAPM is a model which derives the theoretical required expected return (i.e., discount rate) for an asset in a market, given the risk-free rate available to investors and the risk of the market as a whole. The CAPM is usually expressed:

$$r_i - r_f = \beta_i (ar{r}_M - r_f)$$

where $r_f$ is the rate of return on the risk free asset and $\bar{r}_M$ is the expected return on the market portfolio. $\beta_i$, Beta, is the measure of asset sensitivity to a movement in the overall market; Betas exceeding one signify more than average "riskiness" in the sense of the asset's contribution to overall portfolio risk; betas below one indicate a lower than average risk contribution. While $\bar{r}_M - r_f$ is the market premium, the expected excess of the market portfolio’s expected return over the risk-free rate.

This equation can be statistically estimated using the following regression equation:

$$r_i - r_f = \alpha_i + \beta_i (\bar{r}_M - r_f) + \varepsilon_i$$

where $\alpha_i$ is called the asset's alpha, $\beta_i$ is the asset's beta coefficient.
Once an asset's expected return, $\bar{r}_i$, is calculated using CAPM, the future cash flows of
the asset can be discounted to their present value using this rate to establish the correct price for
the asset. A riskier stock will have a higher beta and will be discounted at a higher rate; less
sensitive stocks will have lower betas and be discounted at a lower rate. In theory, an asset is
correctly priced when its observed price is the same as its value calculated using the CAPM
derived discount rate. If the observed price is higher than the valuation, then the asset is
overvalued; it is undervalued for a too-low price.

**Johnson S_u 4-Parameter Probability Distribution**

Given a continuous random variable $X$ whose distribution is unknown and is to be
approximated, Johnson (1949) proposed a set of normalizing translations. These translations
have the following general form

$$ Z = \gamma + \delta \cdot g \left( \frac{X - \xi}{\lambda} \right) $$

(3.6)

where $Z$ is a standard normal random variable, $\gamma$ and $\delta$ are shape parameters, $\lambda$ is a scale
parameter, $\xi$ is a location parameter and $g \,(\cdot)$ is one of the following functions, each one defining
a family of distributions:

$$ g(y) = \begin{cases} 
\ln(y), & \text{lognormal distribution} \\
\ln \left( y + \sqrt{y^2 + 1} \right), & S_u \text{ unbounded distribution} \\
\ln \left( \frac{y}{1 - y} \right), & S_B \text{ bounded distribution} \\
y, & \text{Normal distribution} 
\end{cases} $$

(3.7)

While the $S_u$ distributions are defined in an unlimited range in both directions, for the bounded
distributions the variable is bounded in both directions. After estimating parameters, the
calculation of quantile or tail probability is simple, because these distributions come from a simple transformation of a normal distribution.

Let’s consider first the $S_U$ translation function

$$g(y) = \ln \left( y + \sqrt{y^2 + 1} \right) = \sinh^{-1}(y)$$  \hspace{1cm} (3.8)

where,

$$Z = \gamma + \delta \cdot \sinh^{-1}\left( \frac{X - \xi}{\lambda} \right)$$  \hspace{1cm} (3.9)

where $\lambda$, must be positive. The shape of the distribution of $X$ depends only on the parameters $\gamma$ and $\delta$, so the distribution of the variable $Y = \frac{X - \xi}{\lambda}$ has the same shape as that of $X$, and we can write

$$Z = \gamma + \delta \cdot \sinh^{-1}(Y)$$  \hspace{1cm} (3.10)

Johnson's $S_U$-distribution can cover a wide range of skewness and kurtosis values. In fact, Johnson constructed tables in which he computes $\gamma$ and $\delta$ in terms of skewness and kurtosis. The expected value and the lower central moments of $Y$ are given by the following equations:

$$\mu'_1(Y) = \omega^{1/2} sinh(\theta)$$  \hspace{1cm} (3.11)

$$\mu'_2(Y) = \frac{1}{2} (\omega - 1)(\omega \cosh(2\theta) + 1)$$  \hspace{1cm} (3.12)

$$\mu'_3(Y) = -\frac{1}{4} \omega^2 (\omega - 1)^2 (\omega(\omega - 2) \sinh(3\theta) + 3 \sinh(\theta))$$  \hspace{1cm} (3.13)

$$\mu'_4(Y) = -\frac{1}{8} (\omega - 1)^2 (\omega^2(\omega^4 + 2\omega^3 + 3\omega^2 - 3) \cosh(4\theta) + 4\omega^2(\omega + 2) \cosh(2\theta) + 3(2\omega + 1))$$  \hspace{1cm} (3.14)
where $\omega = \exp(\delta^2)$ and $\theta = \frac{Y}{\delta}$. Observe that when $\theta = 0$ we have $\mu_3(Y) = 0$ and so the
distribution is symmetric. Note also that $\omega > 1$ and $\mu_3$ has opposite sign to $\gamma$. The skewness and
kurtosis of $Y$, which we denote respectively as $\sqrt{\beta_1}$ and $\beta_2$ are given by:

$$\sqrt{\beta_1} = \frac{\mu_3}{\mu_2^{3/2}}$$  \hspace{1cm} (3.15)

$$\beta_2 = \frac{\mu_4}{\mu_2^2}$$  \hspace{1cm} (3.16)

Knowing our target values for skewness and kurtosis for the variable $Y$, the problem is to obtain
estimates the parameters $\gamma$ and $\delta$. This can be done in different ways. We can use the tables
computed by Johnson, but these are limited and often need second order interpolation
techniques. Another possibility is to use equations (3.7) - (3.10) to obtain estimates for $\gamma$ and $\delta$.
The efficiency of this method will depend on the rate of convergence of the algorithm used to
find a solution to the set of equations. Some algorithms for approximating these solutions have
been given by Hill, Hill & Holder (1976).

The probability distribution function of a $S_u$ distributed variable $X$ is given by the equation:

$$f_X(x) = \frac{\delta}{\lambda \sqrt{2\pi}} \exp\left[\frac{-1}{2} \left(\gamma + \delta \sinh^{-1}\left(\frac{x - \xi}{\lambda}\right)\right)^2\right]$$ \hspace{1cm} (3.17)

And the cumulative distribution function of a $S_u$ distributed variable $X$ is given by the equation:
\[ F(x) = \Phi \left( \gamma + \delta \ln \left( \frac{Z}{1 - Z} \right) \right) \] (3.18)

where \( z = \frac{x - \xi}{\lambda} \) and \( \Phi \) is the Laplace Integral.

The use of the families described above (and many others not mentioned here for reason of brevity: e.g., Lye and Martin (1993), Philips (1994), Tiku, Islam, and Selcuk (2001)) allows exploration, identification, and comparison of data without imposing over-restrictive models. It may be that a dataset could be fitted reasonably well by a subordinate model of the larger distribution, but generalized distributions include this information without presupposing it. See King and MacGillivray (1999). Johnson’s SU distribution is an additional family of distributions which is worthy of note in the context of partially adaptive regression.

**Procedure for Estimating the Johnson 4P Probability Distribution**

In the Partially Adaptive Estimation method the distribution of errors in the linear regression model belongs to a parametric family of distributions which is adaptable enough to capture a wide variety of probability densities of interest in statistics, economics, physical sciences (e.g., agronomy, ecology, climate science, and energy systems), health sciences, and general management. The primary objective of PAE is to extract from observed data hidden or implied relationships which were missed or neglected by traditional regression analysis; therefore a common effective framework to obtain full error distribution handling capabilities is established and kept operational for a vast range of applications.
We assume that the data are generated in the following scenario

\[ y_i = x_i'\beta + u_i \text{ for } i = 1, 2, ..., n \]

(3.19)

Where \( y_i \) denotes the response variable of the \( i \)-th observation, \( x_i \) is the \( m \times 1 \) \( i \)-th vector of observations of the exogenous variables including, if needed, the intercept term, and \( n > m + 1 \). The symbol \( \beta \) denotes a conformable vector of unknown regression coefficients or regression parameters. Finally, \( u_i \) is the error or residual term corresponding to the \( i \)-th observation. In this chapter we adopt the standard assumption that the \( u_i, i = 1, 2, n \) are unobservable independent and identically distributed random variables. We also assume that errors are independent of the regressors. Equation (3.19) tells us that \( u_i \) is distributed according to the same model regardless of the value assumed by \( x_i \).

Suppose we know that the residuals in Equation (3.19) are distributed according to the probability density function \( f(u, \lambda) \) which, in turn, depends on a vector \( \lambda \) of \( k \) parameters called distributional parameters. In this setting, a random sample \( \{ y_i, x_i, i = 1, 2, n \} \) yields indirect observations on the residuals \( u \) from \( f(u, \lambda) \) obtained as \( (y - X\beta) \) where \( X \) is the design matrix of order \( n \times (m+1) \). \( \lambda \) and \( \beta \) are the true but unknown values of the parameters. The vector \( \lambda \) makes it possible to acquire original and reliable models of the error term, which may be of use in the analysis of the data at hand; it also allows a correct evaluation of the shape of the error distribution, for example, very diverse tail behavior can be described. If the regression hyperplane has an intercept and \( f(u, \lambda) \) is asymmetric, then the estimate of the intercept and the mean of the estimated errors are indistinguishable unless we specify that \( E(u_i) = 0, i = 1, 2, n \). In
the standard scheme of partially adaptive estimation, the error distribution is known up to $\lambda$ so we can obtain efficient estimates using the maximum likelihood (ML) estimation method. The many subordinate models are able to provide a suitable approximation to the true distribution.

Given the observations and the model, we want to minimize

$$S(\beta, \lambda) = -\sum_{i=1}^{n} \ln[f(y_i - x_i'\beta; \beta, \lambda)]$$

over $\beta$ and $\lambda$. A recurrent hypothesis is that the log-likelihood function in (3.20) is differentiable; consequently, if ML estimators exist they must satisfy the following partial differential equations

$$\frac{\partial S(\beta)}{\partial (\beta_j)} = \frac{1}{f(y_i - x_i'\beta; \beta, \lambda)} \frac{\partial [f(y_i - x_i'\beta; \beta, \lambda)]}{\partial (\beta_j)} x_{ij} = 0$$

$$j = 1, 2, \ldots, m + 1$$

(3.21)

And

$$\frac{\partial S(\beta)}{\partial (\lambda_r)} = -\frac{1}{f(y_i - x_i'\beta; \beta, \lambda)} \frac{\partial [f(y_i - x_i'\beta; \beta, \lambda)]}{\partial (\lambda_r)} = 0$$

$$r = 1, 2, \ldots, k$$

(3.22)

Statistical theory shows that, under standard regularity conditions, ML estimators are invariant to parameterization, asymptotically unbiased, consistent and asymptotically efficient irrespective of the sample size and the complexity of the model (this last property means that, in the limit, there is no other unbiased estimator that produces more accurate parameter estimates). Furthermore, the maximum-likelihood method generates, along with the estimates themselves, useful information about the accuracy of the parameter estimates. In fact, likelihood inference offers a
convenient apparatus to establish the large-sample properties of partially adaptive estimators. For instance, suppose that each $x_i$ is redefined as the deviation from its own mean

$$x_{i0} = 1 \quad \text{for} \ i = 1,2,...,n, \quad \sum_{i=1}^{n} x_{ij} = 0 \quad \text{for} \ j = 1,2,...,m$$  \hspace{1cm} (3.23)

The ML estimate for the regression parameters $\beta$ will be asymptotically independent of the ML estimate of the distributional parameters $\lambda$ included in the error distribution (Cox and Hinkley (1968)). However, when the error distribution is asymmetric none of these estimates gives a consistent estimate of the intercept and therefore, the corresponding prediction of a conditional mean, given the repressors, is also inconsistent. The estimates of the other regression parameters are consistent, but they may lose their high efficiency. If the design matrix $X$ has its columns centered, then the intercept is absorbed in the function.

The estimate of the intercept needs a bias-correction when $E(u)$ is not equal to zero. Since the true distribution function of the errors does not necessarily belong to the hypothesized family, $f(u, \lambda)$, the minimization of Equation (3.3) should more precisely be called the pseudo or quasi maximum likelihood method (Gourieroux, Monfort, and Trognon (1984)). However, if the estimated density approximates the underlying distribution well, the efficiency is expected to be close to that of the maximum likelihood estimation based on knowledge of the actual distribution of the errors.

**Parameters Estimation**

When the density function is known, the maximum likelihood estimators are solutions of Equation (3.21-3.22) with respect to the parameters $\beta_i$, $i = 1, 2, m$ and $\lambda_j$, $j = 1, 2, k$. Likelihood functions are rarely sufficiently regular, e.g., convex, so that it is not usually possible to obtain a
closed-form solution of the likelihood equations and computationally intensive procedures are required. This is particularly true in the area of partially adaptive estimation because the “flexible” functional forms employed to model the error distribution are highly non-linear and include a large number of parameters. Perhaps, it is useful to recall that these parameters are not an end in themselves, but are necessary tools for acknowledging and capturing characteristics associated with many phenomena of statistical interest. However, the widespread availability of versatile and powerful software packages and the improved performance and reduced costs of home computing platforms on which to run them, encourage the regular use of nonlinear parameter estimation when necessary.

The technique used most often is the direct minimization of $S(\beta, \lambda)$ reported in (3.20) in which regression and distributional parameters are estimated simultaneously. Most iterative algorithms for numerical iterative optimization of an objective function use the Gauss-Newton method, steepest descent method, or a combination of these two methods. These procedures frequently incorporate a one-dimensional search algorithm and an option for generalized inverses.

The usual process starts from an initial estimate of the entire set of parameters; with each iteration the estimates are refined by computing a correction factor for each parameter by using the information in the gradient and in the Hessian (analytically or numerically determined); iteration ceases when the gradient is sufficiently close to zero or the correction factors become sufficiently small. A Newton-Raphson or a quasi-Newton method works well and generates asymptotic standard errors as a by-product of the estimation procedure. Such algorithms are not immune from common weaknesses: local optima, inappropriate starting values, divergence, slow convergence, and solutions outside the feasible range of the parameters; in some cases the
calculation of derivatives is completely impractical except by finite difference approximation. These difficulties are essentially due to the use of a large number of unknowns and to the effect of nonlinearity.

A high degree of non-linearity, in fact, can generate very high variability of the estimates, intense correlation between these estimates, and numerical singularities due to heavy cancellation in the density function of the errors. Furthermore, the basic model often nests simpler models as a limiting case for some parameters that may be difficult to handle numerically.

To circumvent all these difficulties it is often possible to take advantage of special structures that exist in certain types of optimization problems. For instance, if the distribution of the residuals is normal, fitting by maximum likelihood is equivalent to fitting by least squares, but the latter is much simpler. Also, the parameters of the likelihood function need not all be treated as nonlinear; in fact, the replacement of linear parameters by their linear least squares estimates, given the values of the nonlinear parameters, leads to a reduced model involving only nonlinear parameters. (See Lawton and Sylvestre (1971), Oberhofer and Kmenta (1974), Gallant and Goebel (1976)). This can be helpful when the model of the error distribution provides box constraints for the distributional parameters which can be exploited by the optimization algorithm, whereas no significant bounds can be given for the regression parameters.

**Analysis of Financial Data**

Since Fama's (1965) work the financial markets literature has been overflowed by studies about skewness, kurtosis and tail-fatness in the distribution of financial returns. We examine this concept using a data set that consists of 36 electric and electric/gas companies that were continuously publicly traded between January 1990 and December 2004. These include all
publicly traded companies with SIC’s 4911 and 4931. Any stock that stopped trading and did not have continuous returns during the period was removed from the sample. This exclusion involved only one utility stock. Market and utility stock returns are monthly total stock returns that are obtained from the University of Chicago’s Center for Research in Security Prices (CRSP) database. The market is defined by the CRSP value-weighted index that includes all stocks traded on the NYSE, NASDAQ, and the AMEX. We used monthly data to be generally consistent with practitioners’ use of monthly data for estimation. Monthly data resulted in 180 stock return observations for each utility stock and the market. The risk-free rate is the one-month return on the one-month US Treasury Bill. The excess market return is the same as defined in the Fama-French database.

The statistics displayed in Table 3.1 assumed that the returns for each stock are independently and identically distributed. The Normality Tests results for each of 36 Electric and Gas company stock return are summarized. Using the JB statistic we rejected the assumption of normality for 28 of the listed stock returns that accounts for a 22.2% success rate. The JB statistics is asymptotically Chi-Squared distributed with two degrees of freedom and has a critical value of 5.99 at the 5% significance level. While applying the Shapiro-Wilk test statistics we rejected only 27 of the returns that accounts for a 25% success rate 33.3 success rate for Anderson Darling test. The results we obtained justified the needs for alternative estimation techniques that would improve the estimates with minimum error.

The measurement of the goodness-of-fit for the distributional regression has two aspects: the degree of proximity between the models adopted to fit the observed residuals to the true distribution that generates data, and, the agreement between observed and estimated responses. We compared the results of the CAPM parameters assuming that the errors followed the Johnson
SU distribution with the OLS CAPM estimates and we observed that the risk parameter have been improved for most stocks.

It should be noted that the estimation of the beta coefficient ($\beta_1$) is important for the risk classification. Table 3.2 summarizes the results, where 36 of the utilities stock show improvement in the estimation of the $\beta_1$'s ranging from 0.04% to 10.65%.

Table 3.1: Normality Test of Stocks

<table>
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<tr>
<th>Ticker</th>
<th>N</th>
<th>Average_Return</th>
<th>Std</th>
<th>Skewness</th>
<th>Kurtosis</th>
<th>JB-P-Value</th>
<th>JB-decision</th>
<th>SW-P-Value</th>
<th>SW-Decision</th>
<th>AD-P-Value</th>
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<td>Reject</td>
<td>0.0050</td>
<td>Reject</td>
</tr>
</tbody>
</table>
The extent of the differences in CAPM beta under normal and Johnson SU distribution are shown in Figure 3.1 in which we rank the top 13 stocks. In our initial test of normality under all three normality test (JB, AD and SW), the six stocks that appeared to have a normal PDF all shows large percent improvement when the Johnson SU PDF was use. The percent increase in the $\beta_1$’s estimates appears to be very volatile across the 36 stocks. Since they differ enough to matter in practice, the use of normality based estimation may not be appropriate. Table 3.2 and Figure 3.3 both displayed the percent change in CAPM Beta under the Johnson Distribution over the Normal distribution. The value weighted portfolio beta for utility stocks during the specific time period was 0.21 and the mean of the percent change between normal beta and Johnson beta is 0.0229 (2.29%). This is a substantial difference, and would lead to a large difference in the estimated cost of capital for the portfolio.

![CAPM Beta Estimates under the Normal and Johnson SU Distribution Assumption](image)
Table 3.2: Percent Change in CAPM Beta

<table>
<thead>
<tr>
<th>Ticker</th>
<th>$\beta_{0\text{-ols}}$</th>
<th>$\beta_{1\text{-ols}}$</th>
<th>$\beta_{0\text{-jsu}}$</th>
<th>$\beta_{1\text{-jsu}}$</th>
<th>$\beta_{JSU-OLS}$</th>
<th>% Δ in $\beta_1$</th>
</tr>
</thead>
<tbody>
<tr>
<td>X1</td>
<td>-0.02459</td>
<td>0.92339</td>
<td>-0.0115</td>
<td>1.0335</td>
<td>0.1101</td>
<td>10.65%</td>
</tr>
<tr>
<td>X2</td>
<td>-0.02066</td>
<td>0.93022</td>
<td>-0.0004</td>
<td>0.9982</td>
<td>0.0680</td>
<td>6.81%</td>
</tr>
<tr>
<td>X3</td>
<td>-0.02195</td>
<td>0.93182</td>
<td>-0.0064</td>
<td>0.9895</td>
<td>0.0576</td>
<td>5.83%</td>
</tr>
<tr>
<td>X4</td>
<td>-0.02364</td>
<td>0.93568</td>
<td>-0.0038</td>
<td>0.9865</td>
<td>0.0508</td>
<td>5.15%</td>
</tr>
<tr>
<td>X5</td>
<td>-0.0038</td>
<td>0.98671</td>
<td>0.0083</td>
<td>1.0397</td>
<td>0.0530</td>
<td>5.09%</td>
</tr>
<tr>
<td>X6</td>
<td>-0.02353</td>
<td>0.93204</td>
<td>-0.0106</td>
<td>0.9818</td>
<td>0.0498</td>
<td>5.07%</td>
</tr>
<tr>
<td>X7</td>
<td>-0.01736</td>
<td>0.94451</td>
<td>-0.0102</td>
<td>0.9855</td>
<td>0.0410</td>
<td>4.16%</td>
</tr>
<tr>
<td>X8</td>
<td>-0.02523</td>
<td>0.92594</td>
<td>-0.0160</td>
<td>0.9647</td>
<td>0.0388</td>
<td>4.02%</td>
</tr>
<tr>
<td>X9</td>
<td>-0.00344</td>
<td>0.98988</td>
<td>0.0147</td>
<td>1.0302</td>
<td>0.0403</td>
<td>3.91%</td>
</tr>
<tr>
<td>X10</td>
<td>-0.0222</td>
<td>0.92098</td>
<td>-0.0134</td>
<td>0.9585</td>
<td>0.0375</td>
<td>3.91%</td>
</tr>
<tr>
<td>X11</td>
<td>-0.02893</td>
<td>0.91938</td>
<td>-0.0179</td>
<td>0.9559</td>
<td>0.0365</td>
<td>3.82%</td>
</tr>
<tr>
<td>X12</td>
<td>-0.02475</td>
<td>0.92287</td>
<td>-0.0124</td>
<td>0.9546</td>
<td>0.0318</td>
<td>3.33%</td>
</tr>
<tr>
<td>X13</td>
<td>-0.02873</td>
<td>0.90952</td>
<td>-0.0172</td>
<td>0.9404</td>
<td>0.0309</td>
<td>3.29%</td>
</tr>
</tbody>
</table>

Figure 3.2: Percent Change in CAPM Beta under the Johnson SU vs. the Normal distribution
The adequacy of the normal distribution can be assessed in several ways. For instance, Islam and Tiku (2004) use the q-q plot of the observed and estimated responses to ascertain the goodness-of-fit for the possible models of the error distribution.

Table 3.3: CAPM beta estimates and Goodness-of-fit statistics from Johnson SU probability distribution

<table>
<thead>
<tr>
<th>Ticker</th>
<th>β₀</th>
<th>β₁</th>
<th>α</th>
<th>R²</th>
<th>Ad.R²</th>
<th>Cor(r,r)</th>
<th>Com(r,r)</th>
<th>tau</th>
<th>Bonf</th>
<th>Rα</th>
<th>psi_α</th>
<th>S_α</th>
<th>(-L)</th>
<th>Sic</th>
</tr>
</thead>
<tbody>
<tr>
<td>X₁</td>
<td>-0.0115</td>
<td>1.0335</td>
<td>3.5526</td>
<td>0.4625</td>
<td>0.4766</td>
<td>0.8564</td>
<td>0.7626</td>
<td>0.7687</td>
<td>0.6765</td>
<td>0.8300</td>
<td>0.8300</td>
<td>0.6390</td>
<td>-132.70</td>
<td>-119.72</td>
</tr>
<tr>
<td>X₂</td>
<td>-0.0004</td>
<td>0.9982</td>
<td>1.0389</td>
<td>0.5567</td>
<td>0.5516</td>
<td>0.8988</td>
<td>0.7927</td>
<td>0.8003</td>
<td>0.7094</td>
<td>0.6226</td>
<td>0.6226</td>
<td>7.9008</td>
<td>-223.23</td>
<td>-210.25</td>
</tr>
<tr>
<td>X₃</td>
<td>-0.0064</td>
<td>0.9895</td>
<td>1.0480</td>
<td>0.6333</td>
<td>0.6291</td>
<td>0.9121</td>
<td>0.7800</td>
<td>0.8257</td>
<td>0.7399</td>
<td>0.6709</td>
<td>0.6709</td>
<td>6.4330</td>
<td>-252.10</td>
<td>-239.12</td>
</tr>
<tr>
<td>X₄</td>
<td>-0.0038</td>
<td>0.9863</td>
<td>1.0703</td>
<td>0.5986</td>
<td>0.5940</td>
<td>0.9173</td>
<td>0.7855</td>
<td>0.8133</td>
<td>0.7236</td>
<td>0.6556</td>
<td>0.6556</td>
<td>6.3471</td>
<td>-235.78</td>
<td>-222.80</td>
</tr>
<tr>
<td>X₅</td>
<td>0.0083</td>
<td>1.0397</td>
<td>1.1403</td>
<td>0.5559</td>
<td>0.5534</td>
<td>0.8973</td>
<td>0.7891</td>
<td>0.7840</td>
<td>0.6954</td>
<td>0.6192</td>
<td>0.6192</td>
<td>10.7158</td>
<td>-398.72</td>
<td>-384.00</td>
</tr>
<tr>
<td>X₆</td>
<td>-0.0106</td>
<td>0.9818</td>
<td>1.0725</td>
<td>0.4910</td>
<td>0.4860</td>
<td>0.8622</td>
<td>0.8073</td>
<td>0.7799</td>
<td>0.6793</td>
<td>0.6066</td>
<td>0.6066</td>
<td>7.7814</td>
<td>-194.70</td>
<td>-181.72</td>
</tr>
<tr>
<td>X₇</td>
<td>-0.0102</td>
<td>0.9855</td>
<td>1.1748</td>
<td>0.5872</td>
<td>0.5825</td>
<td>0.9117</td>
<td>0.8716</td>
<td>0.8194</td>
<td>0.7300</td>
<td>0.6970</td>
<td>0.6970</td>
<td>4.1914</td>
<td>-220.25</td>
<td>-207.27</td>
</tr>
<tr>
<td>X₈</td>
<td>-0.0160</td>
<td>0.9647</td>
<td>1.0314</td>
<td>0.5938</td>
<td>0.5892</td>
<td>0.9146</td>
<td>0.8566</td>
<td>0.8085</td>
<td>0.7159</td>
<td>0.6402</td>
<td>0.6402</td>
<td>7.6318</td>
<td>-238.00</td>
<td>-225.02</td>
</tr>
<tr>
<td>X₉</td>
<td>0.0147</td>
<td>1.0302</td>
<td>3.6397</td>
<td>0.5120</td>
<td>0.5064</td>
<td>0.8736</td>
<td>0.7784</td>
<td>0.7755</td>
<td>0.6823</td>
<td>0.8626</td>
<td>0.8626</td>
<td>0.5524</td>
<td>-182.41</td>
<td>-169.43</td>
</tr>
<tr>
<td>X₁₀</td>
<td>-0.0134</td>
<td>0.9585</td>
<td>1.0830</td>
<td>0.5735</td>
<td>0.5686</td>
<td>0.9052</td>
<td>0.8136</td>
<td>0.7981</td>
<td>0.7031</td>
<td>0.6381</td>
<td>0.6381</td>
<td>6.4674</td>
<td>-226.75</td>
<td>-213.77</td>
</tr>
<tr>
<td>X₁₁</td>
<td>-0.0179</td>
<td>0.9559</td>
<td>1.2061</td>
<td>0.5877</td>
<td>0.5830</td>
<td>0.9118</td>
<td>0.8024</td>
<td>0.8052</td>
<td>0.7158</td>
<td>0.6823</td>
<td>0.6823</td>
<td>3.8787</td>
<td>-240.69</td>
<td>-227.70</td>
</tr>
<tr>
<td>X₁₂</td>
<td>-0.0124</td>
<td>0.9546</td>
<td>1.1136</td>
<td>0.6262</td>
<td>0.6220</td>
<td>0.9281</td>
<td>0.7692</td>
<td>0.8221</td>
<td>0.7330</td>
<td>0.6892</td>
<td>0.6892</td>
<td>4.9175</td>
<td>-255.42</td>
<td>-242.43</td>
</tr>
<tr>
<td>X₁₃</td>
<td>-0.0172</td>
<td>0.9404</td>
<td>1.0157</td>
<td>0.5697</td>
<td>0.5649</td>
<td>0.9032</td>
<td>0.8176</td>
<td>0.8026</td>
<td>0.7115</td>
<td>0.6205</td>
<td>0.6205</td>
<td>8.1809</td>
<td>-216.95</td>
<td>-203.96</td>
</tr>
</tbody>
</table>

We focus on the index below:

$$
\psi_a = 1 - \frac{\sum_{i=1}^{n} |y_i - x_i (\beta) - Q(p_{r_i}, \lambda)|^\alpha}{\sum_{i=1}^{n} |y_i - \theta_\alpha|^\alpha}
$$

(3.24)
The index $\psi_a$ is attractive for a number of reasons: it is dimensionless and varies in the $[0, 1]$ interval; it has an intuitively reasonable interpretation. Before accepting the more complicated models, we need to ask whether the improvement in goodness-of-fit is more than we had expected by chance. If the distributional regression model were really correct then one should find values of $\psi_a$ close to one; conversely, if $\psi_a$ is near to zero, the regression plan determined by minimizing the Minkowski metric under the given distribution of errors is most likely to be wrong. Using the stock data we observe an average $R_a$ of 0.7264, minimum of 0.5596 and a maximum of 0.9644 as shown in Table 3.3. These findings lend support to the argument that the normal assumption is misleading. Table 3.3 contains other goodness of fit statistics that were used to determine the goodness of fit of the distribution.

Conclusion

We have shown that the beta estimates under the Johnson SU Probability Distribution along with the use of partial estimation techniques, outperform the beta estimates form the OLS estimation under normal assumption. Large estimation differences indicate departure from normality. Hence, the use of the true PDF that characterized the stock returns along with an alternative estimator, PAE. An essential task of partially adaptive estimation in CAPM analysis is to screen a large number of potential error distributions to select models which fit the information contained in the response variable both efficiently and concisely. Since estimates that are optimal for one residuals behavior may be quite inadequate for another, owing to differences in the tails and asymmetries, it is desirable to have a procedure that is sufficiently tractable over a vast range of different distributions.

The PAE estimates substantially improve upon OLS estimates in our finite sample applications of CAPM, particularly since the data errors are unevenly distributed around the
mean, or show peakedness and/or fat tails. Therefore OLS is not an efficient estimator of beta. We have shown that the estimates with the Johnson distribution are routinely computable. We also have shown that there are large percent changes in the CAPM beta estimates and lastly it appears that the error model under the Johnson distribution does have potential to outperform that of the Normal distribution.

The results of the work reported above suggest that beta systematic risk measure calculated by CAPM is very sensitive and unstable within a specific sector of the market. These finding have serious implication in investment. If an investment analyst includes the use of CAPM beta in his/her optimal strategy, the following statistical procedure is recommended.

1. Identify the correct probability distribution function that best characterized the historical data of interest.
2. Use the Best estimation technique such as PAE to estimate the parameters of the PDF.
3. Include the PDF chosen in the CAPM assumption and calculate the optimal coefficients alpha and beta.
4. Repeat the procedure over different time intervals and examine the consistency of the beta over time prior to making a decision.

Furthermore, the suggested statistical procedure is unique to the specific stock and hence it has the potential to contribute to the overall reduction in decision error in the stock market. Also in an environment where the stocks are traded infrequently and less data is available, normally referred to as a thin trading environment. Johnson Probability distributions can also be used as a tool to analyze and model the non-normal behavior of hedge fund indices.
Chapter 4: Parametric Statistical Analysis of Belize’s Rainfall

Introduction

Belize is situated on the Caribbean coast of Central America with Mexico to the North and Guatemala to the west and south. It lies between 15º45´ and 18º30´N and 87º30´ and 89º15´W. The terrain is low and flat along coastal areas and in some northern regions of the country while in the central and southern regions low mountains rise gradually to a height of 3,685 feet. See Figure 4.1.

The climate of Belize is characterized by two seasons: a rainy and a dry season. In Belize, most of the year’s rainfall occurs during the period June to November, that is, the rainy season. It is noted from the graph (Figure 4.2) below that the transition from dry to the rainy is very sharp. Mean annual rainfall across Belize ranges from 60 inches (1524mm) in the north to 160 inches (4064mm) in the south. Except for the southern regions, the rainfall is variable from year to year.

Water is one of the vital natural resources, which plays an important role in our lives, be it agriculture, the tourism industry and domestic. Shortage or excessive rainfall can be very harmful as there will be food scarcity and insecurity, water pollution, erosion, telecommunication problems, etc. All of this could lead to economic loss in a country. Therefore, prior knowledge of the distribution of rainfall intensity is important for drainage pattern design. Proper drainage plays a crucial role in controlling erosion, effective agricultural planning, controlling water pollution, and in sustaining the tourism sector of Belize.
Figure 4.1: Map of Belize showing the location of the stations
The primary goal of this chapter is to analyze actual precipitation data collected at fifteen meteorological stations in Belize. There are other stations but because of data length, we chose only fifteen. We first identify the probability density function (PDF) that best characterizes the behavior, the Wakeby distribution, and then grouped the data using the two seasons in Belize, namely the wet and dry season. We did hypothesis testing to determine whether there is a distinction between the two seasons.

Probability distributions can be viewed as a tool for dealing with uncertainty. We use the distributions to perform specific calculations, and apply the results to make well-grounded business decisions. However, if you use a wrong tool, you will get wrong results. If you select
and apply an inappropriate distribution (the one that doesn't fit to your data well), your subsequent calculations will be incorrect, and that will certainly result in wrong decisions.

In many industries, such as agriculture; Belize’s major source of income, the use of incorrect models can have serious consequences, such as the inability to complete tasks or projects in time, and faulty engineering designs resulting in the damage of expensive equipment etc. In some specific areas such as hydrology, using appropriate distributions can be even more critical.

To our knowledge no such research has been done in Belize and hence Distribution fitting allows us to develop valid models which can protect us from potential time and money losses which can arise due to invalid model selection, thus enabling us to make better business decisions.

**Descriptive Statistics**

Rainfall in Belize have been measured daily at a series of fixed weather stations since 1960 by the Belize National Meteorological Services. For the purpose of this study, 15 stations were considered (Figure 4-1). There are other stations in Belize that are currently being used however we didn’t include them because of lack of data within our time frame.

A summary of the monthly rainfall for the 15 stations for period 1964-2011 is presented in Figure 4.2. For all the 15 stations the precipitation typically displays a right skewed and leptokurtic (Figure 4.3). Descriptive statistics of Belize’s precipitation by year are presented in Table 4-1. The annual mean ranges from 3.67 mm to 7.95 mm, while the median ranges from 2.24 mm to 7.72 mm. In every year the mean is greater than the median, indicating that the mean
is influenced by the higher precipitations that are typically observed in the wet season. This is expected given the skewness of the data in Figure 4-2. Positive skewness indicates that values located to the right of the mean are more spread out than are values located to the left of the mean. Negative skewness indicates that values located to the left of the mean are more spread out than are values located to the right of the mean. Inspection of the skewness values in Table 4-1 reveals that, as anticipated, all individual years exhibit right skewness, with skewness values ranging from 0.11 to 4.26. This finding is consistent with the plot of all data (Figure 4-2).

Kurtosis is a measure of the degree of the peakedness of a distribution. A kurtosis measure greater than zero signals a distribution that is more peaked and has tails which are wide relative to the normal distribution. This distribution is said to be leptokurtic. A distribution that is less peaked and has narrower tails relative to the normal distribution is said to be platykurtic.

The normal distribution has a kurtosis value of zero and is said to be mesokurtic. As can be seen in Table 4-1, precipitation data for Belize is leptokurtic for all years between 1960 and 2011. The box-and-whisker plot confirms the observations of the plots and tables above, that the data are skewed to the right.
Table 4.1: Descriptive statistics for the stations

<table>
<thead>
<tr>
<th>Stations</th>
<th>Statistic</th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Statistic</td>
<td>Mean</td>
<td>Median</td>
<td>Variance</td>
<td>Std. Deviation</td>
<td>Skewness</td>
</tr>
<tr>
<td>BELMOPAN</td>
<td></td>
<td>5.74</td>
<td>5.31</td>
<td>20.75</td>
<td>4.56</td>
<td>1.86</td>
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<tr>
<td>CENTFAR</td>
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<td>3.94</td>
<td>10.87</td>
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</tr>
<tr>
<td>LIBERTAD</td>
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<td>3.70</td>
<td>2.92</td>
<td>11.02</td>
<td>3.32</td>
<td>1.34</td>
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<td>MAYAKING</td>
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<td>MELINDA1</td>
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<td>22.27</td>
<td>4.72</td>
<td>1.14</td>
</tr>
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<td>6.97</td>
<td>37.78</td>
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<td>17.93</td>
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<td>SAVANNAH</td>
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<tr>
<td>TOWERHIL</td>
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<td>10.39</td>
<td>3.22</td>
<td>1.16</td>
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<td>8.59</td>
<td>6.29</td>
<td>49.27</td>
<td>7.02</td>
<td>1.08</td>
</tr>
</tbody>
</table>
Figure 4.3: Histograms of monthly precipitation from sampling stations in Belize

Figure 4.4: Box plot for the 15 Stations
Table 4.2: Descriptive statistics for annual rainfall in Belize 1960-2011

<table>
<thead>
<tr>
<th>Year</th>
<th>Mean</th>
<th>Median</th>
<th>Std. Error of Mean</th>
<th>Std. Deviation</th>
<th>Kurtosis</th>
<th>Skewness</th>
</tr>
</thead>
<tbody>
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<td>1960</td>
<td>5.07</td>
<td>5.04</td>
<td>0.99</td>
<td>3.43</td>
<td>1.54</td>
<td>0.99</td>
</tr>
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<td>1961</td>
<td>6.62</td>
<td>5.28</td>
<td>1.57</td>
<td>5.45</td>
<td>3.42</td>
<td>1.73</td>
</tr>
<tr>
<td>1962</td>
<td>5.93</td>
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The Wakeby distribution (WAD), defined by Thomas and introduced by Houghton (1977), is defined by the quantile function

\[
x(F) = \xi + \frac{\alpha}{\beta} [1 - (1 - F)^{\beta}] \frac{\gamma}{\delta} \frac{1}{[1 - (1 - F)^{-\delta}]},
\]

(4-1)

where \( F = F(x) = P(X \leq x) \) is the cumulative distribution function. The parameterization explicitly exhibits the WAD as a generalization of Pareto distribution when \( \alpha = 0 \), or \( \gamma = 0 \), and gives estimates of the \( \alpha \) and \( \gamma \) parameters that are more stable under small perturbations of the data. The domains of the parameters are:

\[
\xi \leq x \leq \infty \text{ if } \delta \geq 0 \text{ and } \gamma > 0
\]
\[ \xi \leq x \leq \xi + \frac{\alpha}{\beta} + \frac{\gamma}{\delta} \text{ if } \delta < 0, \text{ or } \gamma = 0. \]

This distribution is defined by five parameters, more than most of the common systems of distributions. This allows for a wider variety of shapes, and so a reasonably good fit to a sample might be expected. Actually, by suitable choice of parameter values of WAD, it is possible to mimic the extreme value, log-normal, generalized Pareto and log-gamma distributions. Empirical evidence, in relation to the condition of separation (Matalas et al., 1975), suggests that the distributions of floods are more nearly Wakeby-like with $\beta > 1$ and $\gamma > 0$ (i.e., long stretched upper tails) than like any of the other more commonly suggested flood distributions (Houghton, 1978; Landwehr et al., 1978). In addition, WAD provides a plausible description of precipitation sequences, and it also provides a means for representing the seemingly long, stretched upper tail structures of flood distributions, as well as the tail structures of distributions of other hydrologic phenomena (Landwehr et al., 1980). Thus WAD can credibly be considered a parent hydrology distribution. Because of the above reasons, WAD is widely and successfully used in hydrology, especially for the modelling of extreme events. Recently, Wilks and McKay (1996) concluded that WAD provided the best representations of extreme snowpack water equivalent values, based on the performance evaluation of a suite of theoretical probability distributions.

For estimation of the five parameters of WAD, the method of $L$-moments estimation (Hosking, 1990) has been used. In this study, attempts to use WAD with the method of $L$-moments estimates ($L$-ME), on the Belize’s rainfall data (monthly average precipitation) at 15 weather stations Belize have been made to obtain reliable quantile estimates.
The Wakeby Probability distribution is a very flexible five-parameter distribution (Pilon and Harvey, 1994). It can assume shapes that other distributions cannot describe. While this has been seen as an advantage, it means that records with several years of extreme data can affect the shape of this distribution to a greater extent than other distributions.
L- Moment Estimation of Wakeby Probability Distribution

For estimation of the five parameters of WAD, the method of L-moments estimation (Hosking, 1990) has been used. Since the distribution function $F(x)$ of WAD is not explicitly defined, the maximum likelihood estimates (MLE) of parameters are not easily obtained (see Park and Jeon, 2000, for computing MLE). Thus the method of probability weighted moments (PWM) estimation was introduced by Greenwood et al. (1979) for estimation of parameters of the distributions (like WAD) whose inverse form $x = x(F)$ is explicitly defined. Since the L-moments are simple linear combinations of special cases of PWMs, the method of L-moments estimation (L-ME) can be viewed as equivalent to the method of PWM estimation. L-Moments are more convenient, however, because they are more directly interpretable as measures of the scale and shape of the probability distribution. The main advantages of using L-ME are that the parameter estimates are more reliable than the method of moment’s estimates, particularly from small samples, and are usually computationally more tractable than MLE. Furthermore, due to the use of linear moments instead of the conventional product moments and being resistant to the presence of outliers (which may be present in the sample due to the occurrence of heavy rainfall and typhoon events), the method is quite robust.

The (population) L-moments of WAD are, following Hosking (1986):

$$\lambda_1 = \xi + \frac{\alpha}{1 + \beta} + \frac{\gamma}{\delta - 1}$$

(4-2)

$$\lambda_2 = \frac{\alpha}{(1 + \beta)(2 + \beta)} + \frac{\gamma}{(1 - \delta)(2 - \delta)}$$

(4-3)
\[
\lambda_3 = \frac{\alpha (1 - \beta)}{(1 + \beta)(2 + \beta)(3 + \beta)} + \frac{\gamma (1 + \delta)}{(1 - \delta)(2 - \delta)(3 - \delta)}
\]

(4-4)

\[
\lambda_4 = \frac{\alpha (1 - \beta)(2 - \beta)}{(1 + \beta)(2 + \beta)(3 + \beta)(4 + \beta)} + \frac{\gamma (1 + \delta)(2 + \delta)}{(1 - \delta)(2 - \delta)(3 - \delta)(4 - \delta)}
\]

(4-5)

\[
\lambda_r = \frac{a \Gamma(1 + \beta) \Gamma(r - 1 - \beta)}{\Gamma(1 - \beta) \Gamma(r + 1 + \beta)} + \frac{\gamma \Gamma((1 - \delta) \Gamma((r - 1 + \delta)}{\Gamma(1 + \delta) \Gamma(r + 1 + \delta)}, \quad r \geq 5
\]

(4-6)

The sample L-moments are obtained from observations: see Hosking (1990) for the formulas. Now, analogously to the usual method of moment’s estimations, the ‘method of L-moments estimation’ (L-ME) obtains parameter estimates by equating the first \(p\) (number of parameters) sample L-moments to the corresponding population L-moments. Since no explicit solution of simultaneous equations is possible in WAD, the equations can be solved by Newton–Raphson iteration. Landwehr et al. (1979) derived an algorithm to get the estimates in each of the cases: known and unknown. The FORTRAN program (PELWAK) provided by Hosking (1997) basically uses the method of Landwehr et al. (1979). First a solution is sought in which all five parameters are estimated, as functions of the first five L-moments. If no solution is found due to convergence failure, the parameter it is set to zero and a solution is sought in which the other four parameters are estimated as functions of the first four L-moments. If this too is unsuccessful, then a generalized Pareto distribution is fitted instead, using the first three L-moments. Note that, when \(\alpha=0\) or \(\gamma=0\) (but not simultaneously) in WAD, Equation (4.1) is reduced to the following quantile function of the generalized Pareto distribution:

\[
x(F) = \xi + \alpha \frac{[1 - (1 - F)^k]}{k}
\]

(4-7)
The probability function, the parameter estimates (L-ME) of WAD, and Kolmogorov–Smirnov’s (K–S) goodness-of-fit statistic D at each station are given in Tables 4.3. The p-values of K–S Ds are at least 0.35, which shows that WAD is acceptable for each of the stations. Figure 3-3 shows the relative frequency histogram of each station.

Result of Fitting The Wakeby Probability Distribution Function

Table 4.3: Station codes, parameters estimates of Wakeby Distribution, K_S statistics and P-Value computed from Stations.

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<th>Stations</th>
<th>BEST- FIT Distribution</th>
<th>PARAMETERS</th>
<th>Goodness of fit</th>
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<td></td>
<td></td>
<td>$\xi$</td>
<td>$\alpha$</td>
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Table 4.4: Best fit probability distribution of clustered data

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<th>PARAMETERS</th>
<th>Goodness of fit</th>
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Hydrological data are often asymmetrical and right skewed. Results from fitting data, from the meteorological stations and the results represented in short by the following paragraphs. The method discussed above is used to estimate the parameters of the Wakeby Distribution for the period 1960-2012. In addition to the Wakeby Distribution, efforts were made to test the performance of other popular distributions such as lognormal and Weibull distribution. The estimated parameters for the Wakeby Distribution are presented in Table 4.3. From the Table 4.3, it appears that the data fits the identified Wakeby distribution well. Table 4.5 compares the actual observed average rainfall for each station to that of the estimated average rainfall using our proposed model. It is showed that the range of the difference is from (0 - 48.59) %, with an average difference of 20.52%. In Table 4.6, we compared the actual average monthly rainfall to

Table 4.5: Comparison of station’s observed average vs. proposed model estimated average rainfall

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<td>3.70</td>
<td>5.39</td>
<td>37.22</td>
</tr>
<tr>
<td>MAYAKING</td>
<td>6.39</td>
<td>6.39</td>
<td>0.00</td>
</tr>
<tr>
<td>MELINDA1</td>
<td>6.14</td>
<td>6.22</td>
<td>1.24</td>
</tr>
<tr>
<td>MIDDELE</td>
<td>7.94</td>
<td>8.06</td>
<td>1.57</td>
</tr>
<tr>
<td>POMONA01</td>
<td>7.20</td>
<td>7.90</td>
<td>9.32</td>
</tr>
<tr>
<td>PSWGIA01</td>
<td>5.43</td>
<td>6.05</td>
<td>10.83</td>
</tr>
<tr>
<td>PUNTAGOR</td>
<td>10.51</td>
<td>6.60</td>
<td>45.67</td>
</tr>
<tr>
<td>RIOBRAVO</td>
<td>3.95</td>
<td>6.49</td>
<td>48.59</td>
</tr>
<tr>
<td>SAVANNAH</td>
<td>6.54</td>
<td>6.49</td>
<td>0.89</td>
</tr>
<tr>
<td>SPANISHL</td>
<td>4.31</td>
<td>6.29</td>
<td>37.43</td>
</tr>
<tr>
<td>STJOHNSC</td>
<td>4.81</td>
<td>6.24</td>
<td>25.87</td>
</tr>
<tr>
<td>TOWERHIL</td>
<td>3.81</td>
<td>6.15</td>
<td>47.01</td>
</tr>
<tr>
<td>TRDP0001</td>
<td>8.59</td>
<td>5.96</td>
<td>36.19</td>
</tr>
</tbody>
</table>
Table 4.6: Comparison of station’s observed average vs. PRECIS model forecasted average rainfall

<table>
<thead>
<tr>
<th>Stations</th>
<th>Mean</th>
<th>PRECIS</th>
<th>% Difference</th>
</tr>
</thead>
<tbody>
<tr>
<td>BELMOPAN</td>
<td>5.74</td>
<td>8.06</td>
<td>33.64</td>
</tr>
<tr>
<td>CENTFAR</td>
<td>4.45</td>
<td>6.63</td>
<td>39.44</td>
</tr>
<tr>
<td>LIBERTAD</td>
<td>3.70</td>
<td>5.73</td>
<td>43.09</td>
</tr>
<tr>
<td>MAYAKING</td>
<td>6.39</td>
<td>9.26</td>
<td>36.62</td>
</tr>
<tr>
<td>MELINDA1</td>
<td>6.14</td>
<td>9.05</td>
<td>38.32</td>
</tr>
<tr>
<td>MIDDELSE</td>
<td>7.94</td>
<td>11.12</td>
<td>33.43</td>
</tr>
<tr>
<td>POMONA01</td>
<td>7.20</td>
<td>10.80</td>
<td>40.04</td>
</tr>
<tr>
<td>PSWGIA01</td>
<td>5.43</td>
<td>8.16</td>
<td>40.18</td>
</tr>
<tr>
<td>PUNTAGOR</td>
<td>10.51</td>
<td>15.92</td>
<td>40.98</td>
</tr>
<tr>
<td>RIOBRAVO</td>
<td>3.95</td>
<td>5.59</td>
<td>34.36</td>
</tr>
<tr>
<td>SAVANNAH</td>
<td>6.54</td>
<td>10.05</td>
<td>42.21</td>
</tr>
<tr>
<td>SPANISHL</td>
<td>4.31</td>
<td>****</td>
<td>****</td>
</tr>
<tr>
<td>STJOHNSC</td>
<td>4.81</td>
<td>7.19</td>
<td>39.63</td>
</tr>
<tr>
<td>TOWERHIL</td>
<td>3.81</td>
<td>5.70</td>
<td>39.86</td>
</tr>
<tr>
<td>TRDP0001</td>
<td>8.59</td>
<td>12.66</td>
<td>38.30</td>
</tr>
</tbody>
</table>

The PRECIS forecasted values for the stations. This second comparison the range of the difference is (33.64 - 40.98) %, with an average difference of 38.58 in the average monthly rainfall for the stations. The selection of an appropriate frequency distribution for extreme precipitation over Belize is made with an aim to identify a distribution that best fits the observed data.

**Examining Belize’s Wet and Dry Seasons**

Since there are two distinct rainfall seasons in Belize, we test whether there is a significant difference between the Wet and Dry season in Belize. The Kruskal Wallis test and the Kolmogorov Smirnov test suggested that there is a statistical significant difference between the two seasons hence the need to further examine the p. d. f. of the two seasons. Table 4.8 shows that for the dry season the best fit model is the Wakeby distribution; however, for the Wet season
from June to November the average rainfall in Belize from 1964-2011 follows a Generalized extreme value distribution. Figure 4.7 and 4.8 shows the p.d.f. of the two seasons.

Table 4.7: Hypothesis Test Summary

<table>
<thead>
<tr>
<th>Null Hypothesis</th>
<th>Test</th>
<th>Sig.</th>
<th>Decision</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 The distribution of AMR is the same across categories of Season.</td>
<td>Independent Samples Kolmogorov-Smirnov Test</td>
<td>.000</td>
<td>Reject the null hypothesis.</td>
</tr>
<tr>
<td>2 The distribution of AMR is the same across categories of Season.</td>
<td>Independent Samples Kruskal-Wallis Test</td>
<td>.000</td>
<td>Reject the null hypothesis.</td>
</tr>
</tbody>
</table>

Asymptotic significances are displayed. The significance level is .05.

Table 4.8: Best Fit Model for the monthly rainfall

<table>
<thead>
<tr>
<th>Season</th>
<th>Best fit Distribution</th>
<th>Kolmogorov Smirnov Statistics</th>
<th>P-value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Dry</td>
<td>Wakeby</td>
<td>0.0112</td>
<td>.86425</td>
</tr>
<tr>
<td>Wet</td>
<td>Gen. Extr</td>
<td>0.01264</td>
<td>.75285</td>
</tr>
</tbody>
</table>
Figure 4.8: Probability Density function for Belize’s wet season

Figure 4.9: Probability Density function for Belize’s dry season
Conclusion

The determination of the best fit distribution to represent the rainfall process in stations of Belize is discussed in this paper. An extensive search comparing several distributions such as Wakeby, lognormal, gamma, Weibull, Generalized Pareto, Dugan and many other distributions have been used on the monthly average rainfall data from 1960 to 2011. The selection of the best fit distribution is done by examining the minimum error produced by the Kolmogorov Smirnov (KS) goodness of fit test. Based on the results of KS goodness of fit test, Wakeby distribution is the most suitable to describe the rainfall patterns in the stations of Belize as the error produced is the minimum. There were three stations, Belmopan, Libertad and Rio Bravo for which the Wakeby distribution was ranked as second best distribution.

The cluster analysis identifies eight clusters in Belize’s rainfall using the Ward’s Method (See Table 4.4). Four of the clusters are somewhat notable because their clustering is based on their regional location such north, south, central and west. Looking at the individual best fit probability distribution functions of the clusters, notably the Wakeby distribution base on the Kolmogorov Smirnov test statistics fitted the data very well. Therefore, the best fit probability function is the Wakeby distribution. The variation exhibit permits for the further study of the underlying factors present in the different geographical area in Belize.
Chapter 5: Statistical Models for Forecasting Tourists Arrival in Belize

Introduction

In the previous chapter we understand the behavior of rainfall of Belize and this is very important to tourism. Tourism is vitally important to the entire Belizean economy, contributing 26% of Belize's gross domestic product in 2006 and 50% in 2015. In most of coastal Belize, tourism has completely replaced fishing as the primary source of income for all but a very few residents. Tourism is the number one foreign exchange earner in this small economy, followed by exports of marine products, citrus, cane sugar, bananas, and garments. However, this sector is exposed to the vagaries of international economics and is severely affected in recession years. Despite the drop in arrivals in 2009 the industry experienced many record breaking arrivals which led to an overall growth during the years 2011-2015, an outstanding period for the Tourism Industry in Belize.

The development of tourism in Belize was premised originally on the niche marketing of the country to high end, stay-over visitors interested in a pristine, natural, land and marine environment, otherwise known as eco-tourism. The consequent pressures on tourism facilities, sites and regulatory capacity generated by these day visitors sparked controversial debates on the potential negative impact on the niche stay-over market segment, highlighted the problems arising from the lack of a cohesive, comprehensive, national framework for tourism/cruise development and raised questions on the actual net benefits accruing to Belize from mass market, cruise tourism. The development of the tourism industry in Belize was built through the development of the overnight sector. Over the past five years, Belize overnight tourism sector
has seen consistent growth, and particularly very strong performances in 2012-2014, with 2014 being the most positive year of overnight tourism in Belize in the last ten years.

The forecast of tourists’ arrival is important since it would enable the tourism industry of Belize to adequately prepare for any number of arrivals at any future date. The benefits of accurate forecasts are well documented in tourism forecasting literature (Molly 1991). Accurate forecasts are valuable to both the private and public sectors. Forecasting is crucial for the private sector in planning to avoid shortages or surpluses in goods and services. Time series analysis and modelling plays a very important role in forecasting, especially when our initial stochastic realization is nonstationary in nature.

Time series analysis is one of the major areas in statistics that can be applied to many realistic problems. In the present chapter, we begin with a description of the structure of the Belizean economy and the importance of tourism in the economy. We then summarize the development of time series modeling and introduce some methodologies that have been developed recently. We also introduce some fundamental concepts that are essential for dealing with time series models. We carry out a statistical comparison of two different time series models by comparing their forecasting and actual residuals.

A true test of a forecasting model is its ability to forecast outside the sample period. We measure the accuracy of the forecasts by withholding the data for the last two years. We use for each model a subset of the data (all observations except the last two years) to forecast the remainder of the known data. For the forecast period, a forecast error is calculated, defined as actual tourist arrivals less forecast tourist arrivals. We then used the mean absolute percentage error (MAPE), as the final measure of forecast accuracy.
Over the past two decades, the study of air travel demand forecasting has attracted considerable attention by researchers. Within the Central American and Caribbean region considerable attention has been given to tourism but not much in terms of statistical driven research. For Belize, the last known study was done by United Nation in 1992 where they forecasted Caribbean tourist data using ARIMA. Among various competing forecasting models, ARIMA has gained popularity and is frequently adopted in empirical studies, because it often outperforms many other econometric and time series methods. Dharmaratne (1995) estimates and validates the ARIMA model for forecasting long-stay visitors in Barbados and suggests that customized model building may be highly rewarding compared to simple or standard methods. Lim and McAleer (1999) use the ARIMA model to explain tourist arrivals from Malaysia to Australia. The HEGY seasonal unit roots test is used to examine stochastic seasonality in the tourism demand series. Their findings, revealing the existence of seasonal unit roots in international tourist arrivals from Malaysia to Australia, is evidence in favor of a varying, rather than constant seasonal pattern. Kulendran and Witt (2003) examine seven forecasting models on international business tourism and suggest that the relative forecasting performance of various models is highly dependent on the length of forecasting horizon and the detection of seasonal unit roots. In addition, the Lim and Pan (2005) study also adopts the ARIMA model to study inbound tourism development in China. A comparison of the forecasting performance of competing models is frequently highlighted in recent tourism demand forecasting literature (Chu 2004, Kulendran and Wong 2005, Coshall 2006). While consensus is not yet achieved, many researchers conclude the ARIMA model, to a great degree, appears the suitable model (Chu 1998, Kim and Song 1998, Kulendran and Witt 2001, Lim and McAleer 2002). For the purpose
of forecasting performance comparison, we choose two models including Seasonal ARIMA and the Holt–Winter method to model inbound tourism arrival in Belize.

**Structure of Belize’s Economy and Importance of Tourism**

With a GDP of $9600 per capita in 2014, Belize is a small, open economy, characterized by a narrow production base, heavy reliance on imports, small range of mostly primary, export commodities and a manufacturing capacity (excluding export sugar and citrus juice manufacturing) limited to production which can profitably meet the domestic demand of its small population base (0.37 million people in 2015).

Up to the 1990’s, the country was highly dependent on sugar exports that accounted for more than 40.0% on average of domestic merchandise exports. Following the oil shock in the late 1970’s and plummeting sugar prices in the early 1980’s, the development of the tourism industry was encouraged as part of a general strategy to diversify the economy, increase foreign exchange earnings, generate employment and so improve the country’s resilience to external shocks.

After more than four decades, some success in reducing dependence on sugar exports and in expanding the tourism industry was achieved. Sugar as a share of domestic exports went from 44.7% in 1984 to 25.1% in 2015 with a low of 10.9% in 2010, in response to higher production of other traditional exports such as citrus and banana and development of nontraditional commodities such as papaya, farmed shrimp and petroleum. Meanwhile, significant foreign and local investments into tourism have gradually raised its economic importance and have contributed to its current substantial level.

The results of the continued tourism expansions are evident. Foreign exchange earnings as a percent of exports of goods and services have increased. Using the SIC categories of “Hotel
and Restaurants” and “Transportation” to proxy tourism’s contribution to GDP. Its share of GDP increased over the same period. Employment in tourism has risen steadily with time. Available data since 1998 showed that employment in tourism rose from one out of every 11 persons in 1998 to one out of every 7 persons by 2014 (BTB 2014).

**Table 5.1: Belize’s Economics as it relates to Tourism**

<table>
<thead>
<tr>
<th>Belize’s Economics as it relates to Tourism</th>
<th>% change '14 vs. '13</th>
<th>2014</th>
<th>2013</th>
<th>2012</th>
<th>2011</th>
<th>2010</th>
</tr>
</thead>
<tbody>
<tr>
<td>Tourist Expenditure (mnBze $)</td>
<td>3.2</td>
<td>773</td>
<td>750</td>
<td>639</td>
<td>514</td>
<td>500</td>
</tr>
<tr>
<td>Tourist Expenditure (mn US $)</td>
<td>3.2</td>
<td>387</td>
<td>375</td>
<td>320</td>
<td>257</td>
<td>250</td>
</tr>
<tr>
<td>Employment in Tourism (SIB)</td>
<td>19,141</td>
<td>18,850</td>
<td>N.D.</td>
<td>N.D.</td>
<td>13,242</td>
<td></td>
</tr>
<tr>
<td>Total Employment (SIB)</td>
<td>4.8</td>
<td>134,421</td>
<td>128,277</td>
<td>N.D.</td>
<td>N.D.</td>
<td>107,484</td>
</tr>
<tr>
<td>Tourism employment as a % of total</td>
<td>-3.1</td>
<td>14.2</td>
<td>14.7</td>
<td>N.D.</td>
<td>N.D.</td>
<td>12.3</td>
</tr>
<tr>
<td>GDP - Current Prices (mnBze $) - revised</td>
<td>4.6</td>
<td>3,398</td>
<td>3,249</td>
<td>3,145</td>
<td>2,978</td>
<td>2,797</td>
</tr>
<tr>
<td>Tourism expenditure as % of GDP</td>
<td>22.8</td>
<td>23.1</td>
<td>20.3</td>
<td>17.2</td>
<td>17.9</td>
<td></td>
</tr>
<tr>
<td>Total</td>
<td></td>
<td>1699</td>
<td>1624.3</td>
<td>1572.6</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Institutional and Policy Framework**

The Belize Tourism Board (BTB) is the implementing arm of the Ministry of Tourism. Responsibility for planning, developing, promoting and regulating the growth of the tourist industry lies with this statutory body whose Board of Directors is comprised of private sector representatives and whose budget is funded through industry taxes.

In addition to the work of the BTB, Government provides assistance mostly through loan funded projects that address critical infrastructural constraints. Between 2000 and 2004, the Government, through a combination of loan, grants and counterpart funds, invested
approximately US$15.0 million to develop and improve a number of major archaeological sites and provide training mostly to tour guides and other service providers. Notably, the improvements to the archaeological sites were designed for a combined maximum of 300,000 cruise and stay-over visitors and did not cater for the explosive growth in cruise arrivals that began in 2002. Various private sector associations, funded through membership fees, protect and lobby for their interests. The Belize Tourism Industry Association (BTIA) was initially set up as an umbrella organization for all service providers. Its membership includes various smaller associations such as the Hotel and Tour Guides Association. The Federation of Cruise Associations of Belize is a recently formed breakaway group consisting of some 800 members spread across 19 associations that include tendering, taxis, handicraft and transportation. The members of this federation did not want their interests diluted by biases in favor of stay-over market interests.

Recognizing the need for a comprehensive framework and more pro-active approach to developing the tourism industry, the Ministry of Tourism commissioned the Blackstone Corporation in 1998 to develop a ten year strategy and action plan to stimulate economic growth, while protecting the country’s environmental and heritage resources and ensuring benefits for the local people.

This first national tourism strategy recommended the continued niche marketing of the country to high-end spenders on an eco-tourism platform that promoted small scale, environmental, cultural and community tourism with strong inter-sectoral linkages. The Blackstone report considered and discarded a mass tourism scenario aimed at quadrupling arrivals to 400,000 by 2008, because it was felt that the environmental degradation and negative cultural impact could destroy the country’s eco-tourism niche. Instead, the proposed strategy
opted for a lower, average, annual growth of 4.0% or minimum target of 120,000 visitors by the end of the first 5 years and a minimum of 140,000 visitors by the end of 2008.

An updated national tourism policy (BTB, 2005) was crafted in 2005 that recommended the non-conflicting co-existence of the niche, stay-over and mass market, cruise segments. The policy assumed that cruise arrivals would stabilize at an annual rate of 1.0mn visitors and cautioned that the expansion of the cruise industry should not jeopardize Belize’s status as an eco-tourism destination. It suggested that selected sites should be designated primarily as cruise visitors’ sites or new sites catering specifically to the cruise market should be developed. Another recommendation was the immediate implementation of ceilings or capacity limits on the number of cruise visitors to designated sites. This policy also called for the development of a long term Tourism Master Plan (a plan of action, cutting across all government ministries and even some private sector stakeholders) to implement the recommendations suggested in the policy paper. To date, no sites have been designated specifically for cruise tourists, nor have capacity limits been adhered to and financing constraints have delayed development of the master plan.

The Government, however, has secured a loan to finance tourism oriented infrastructural projects in selected destinations and has also produced the tourism master plan. It remains to be seen if the needed multi-disciplinary buy-in will be obtained to implement the entire policy rather than just those sections that fall within the purview of the tourism ministry and the BTB, as happened with the 1998 strategy. Notwithstanding the existence of this policy, the sentiment is widely felt especially among the stakeholders in the stay-over market that the explosive growth of cruise tourism has put at risk the country’s niche positioning as a high-end provider of an eco-

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based tourist experience, and its development has not proceeded in a sustainable and environmentally responsible manner.

Significant attention was given to the cruise tourism because of the potential and contributions to the countries’ economy and in 2015 there was a total of 957,975 Cruise Passenger Arrival, this was a minor drop of 1% compared to 2015.

Figure 5.1 shows that Americans continue to be our largest market for visitors, making up 63.1% of the overall arrivals. This followed by Europeans at 12% and Canadians at 7% in 2015.

![Market Share: Jan-Dec 2015](image)

**Figure 5.1: Market Share: Jan – Dec 2015**

**Methodology**

Figure 5.2 shows the actual data used in the model building process and illustrates the high degree of nonlinearity and seasonality and upward trend in time. The time plot shows drop in
2009, and an increase in 2010. There is nothing unusual about the time plot and there appears to be no need to do any data adjustments.

The Monthly data for the period 2000 to 2013 is divided into two periods: (1) data from 2000-2011, yielding 144 observations, are employed to estimate two models for the series; (2) data from 2012-2013 are used for ex post validation purposes referred to as the test data.

![Plot of tourist's arrivals in Belize 2000-2013](image)

**Figure 5.2: Plot of tourist’s arrivals in Belize 2000-2013**

We introduced first the Holt –Winters Exponential Smoothing, since the data exhibits seasonality and trend. We then introduced the seasonal ARIMA model.
Holt-Winters Exponential Smoothing

The idea of exponential smoothing is to forecast future points through an exponentially weighted average of past observation. Holt-Winters exponential smoothing estimates the level, slope, and seasonal component at the current time point. Smoothing is controlled by \( \alpha \), \( \beta \) and \( \gamma \) for the estimates of the level, slope of the trend, and seasonal component, respectively. Parameter values close to zero means that relatively little weight is placed on the most recent observations when making forecasts of future values.

The Holt-Winters model uses a modified form of exponential smoothing. It applies three exponential smoothing formulae to the series. Firstly, the level (or mean) is smoothed to give a local average value for the series. Secondly, the trend is smoothed and lastly each seasonal sub-series (i.e. all the January values, all the February values….. for monthly data) is smoothed separately to give a seasonal estimate for each of the seasons.

The exponential smoothing formulae applied to a series with a trend and constant seasonal component using the Holt-Winters additive technique are:

\[
\begin{align*}
    a_t &= \alpha(Y_t - s_{t-p}) + (1 - \alpha)(a_{t-1} + b_{t-1}) \\
    b_t &= \beta(a_t - a_{t-1}) + (1 - \beta)b_{t-1} \\
    s_t &= \gamma(Y_t - a_t) + (1 - \gamma)s_{t-p}
\end{align*}
\]

where \( \alpha \), \( \beta \) and \( \gamma \) are the smoothing parameters, \( a_t \) is the smoothed level at time \( t \), \( b_t \) is the change in the trend at time \( t \), \( s_t \) is the seasonal smooth at time \( t \) and \( p \) is the number of seasons per year.
The Holt-Winters algorithm requires starting (or initialising) values. Most commonly:

\[
a_p = \frac{1}{p} (Y_1 + Y_2 + \ldots + Y_p)
\]

\[
b_p = \frac{1}{p} \left[ \frac{Y_{p+1} - Y_1}{p} + \frac{Y_{p+2} - Y_2}{p} + \ldots + \frac{Y_{p+p} - Y_p}{p} \right]
\]

\[
s_1 = Y_1 - a_p, \quad s_2 = Y_2 - a_p, \quad \ldots, \quad s_p = Y_p - a_p
\]

the Holt-Winters forecasts are then calculated using the latest estimates from the appropriate exponential smoothings that have been applied to the series. So we have our forecast for time period \( T + \tau \):

\[
\hat{y}_{T+\tau} = a_T + \tau b_T + s_T
\]

where \( a_T \) is the smoothed estimate of the level at time \( T \), \( b_T \) is the smoothed estimate of the change in the trend value at time \( T \) and \( s_T \) is the smoothed estimate of the appropriate seasonal component at \( T \).

As mentioned earlier the Holt-Winters model assumes that the seasonal pattern is relatively constant over the time period. We expected to notice changes in the seasonal pattern and identify this as a potential problem with the model, particularly if long-term predictions are made. In practice this is dealt with by transforming the original data and modelling the
transformed series or using a multiplicative model. The exponential smoothing formulae applied to a series using Holt-Winters Multiplicative models are:

\[ a_t = \alpha \frac{Y_t}{s_{t-p}} + (1 - \alpha)(a_{t-1} + b_{t-1}) \]  

(5-7)

\[ b_t = \beta(a_t - a_{t-1}) + (1 - \beta)b_{t-1} \]  

(5-8)

\[ s_t = \gamma \frac{Y_t}{a_t} + (1 - \gamma)s_{t-p} \]  

(5-9)

The initialising values are:

\[ s_1 = \frac{Y_1}{a_p}, \quad s_2 = \frac{Y_2}{a_p}, \quad \ldots, \quad s_p = \frac{Y_p}{a_p} \]  

(5-10)

So we have our prediction for time period \( T + \tau \):

\[ \hat{y}_{T+\tau} = (a_T + \tau \ b_T)s_T \]  

(5-11)
Figure 5.3: Plot of Tourist arrivals two year forecast

ARIMA Model

The classical ARIMA \((p, d, q)\) is defined as follows

\[
\Phi_p(B)(1-B)^d X_t = \theta_q(B) \epsilon_t
\]

(5-12)

Where \(\{X_t\}\) is the realized time series.

The seasonal ARIMA model incorporates both non-seasonal and seasonal factors in a multiplicative model. One shorthand notation for the model is ARIMA \((p, d, q) \times (P, D, Q)_S\), with \(p =\) non-seasonal AR order, \(d =\) non-seasonal differencing, \(q =\) non-seasonal MA order, \(P = \)seasonal AR order, \(D = \)seasonal differencing, \(Q = \)seasonal MA order, and \(S = \)time span of repeating seasonal pattern. Without differencing operations, the model could be written more formally as

\[
\Phi(B^S) \varphi(B)(X_t - \epsilon_t) = \Theta(B^S) \theta(B) \epsilon_t
\]

(5-13)
The non-seasonal components are:

AR: \( \phi(B) = 1 - \phi_1 B - \cdots - \phi_p B^p \)

MA: \( \theta(B) = 1 + \theta_1 B + \cdots + \theta_q B^q \)

The seasonal components are:

Seasonal AR: \( \Phi(B^S) = 1 - \Phi_1 B^S - \cdots - \Phi_p B^{pS} \)

Seasonal MA: \( \Theta(B^S) = 1 + \Theta_1 B^S + \cdots + \Theta_Q B^{Qs} \)

Note that on the left side of Equation (5.1) the seasonal and non-seasonal AR components multiply each other, and on the right side of Equation (5.1) the seasonal and non-seasonal MA components multiply each.

The order of the seasonal ARIMA model determines the structure of the model and it is essential to have a good methodology in terms of developing the forecasting model. In the present study, we start with addressing the issue of the seasonal sub index \( s \). After we examine the original data, shown by Figure 5.11, we have reason to believe the average monthly tourists arrivals behave as a periodic function with a cycle of 12 months.

Hence, we let the seasonal sub index \( s = 12 \). In time series analysis, one cannot proceed with a model building procedure without confirming the stationarity of a given stochastic realization, thus, we test the overall stationarity of the series by using the method introduced by Kwiatkowski, D., Phillips, P C. B., Schmidt, P., and Shin, Y in 1992, (Kwiatkowski et al., 1992). Once the order of the differencing is identified, it is common for one ARIMA \( (p, d, q) \times (P, D, Q)_s \) model that we have several sets of \( (p, q, P, Q) \) that are all adequately representing a given set of time series. Akaike’s information criterion, AIC, (Akaike, 1974), was first
introduced by Akaike in 1974 plays a major role in our model selecting process. We shall choose the set of \((p, q, P, Q)\) that produces the smallest AIC.

Another important aspect in our model selection process is to determine the seasonal differencing, \(D\), the goal is to select a smaller AIC without complicating the selected model. Hence, we only compute the AIC for both \(D = 0\) and \(D = 1\) based on our previous selection of the orders \((p, d, q, P, Q)\), and choose the model with smaller AIC to be our final model.

Below we summarize the model identifying procedure:

1. Determine the seasonal period \(s\).
2. Check for stationarity of the given time series \(y_t\) by determining the order of differencing \(d\), where \(d = 0, 1, 2, \ldots\), according to KPSS test, until we achieve stationarity.
3. Deciding the order \(m\) of the process, for our case, we let where \(m = 5\)
   \[
   p + q + P + Q \leq m
   \]
4. After \((d, m)\) are selected, lies all possible configurations of \((p, q, P, Q)\) for
   \[
   p + q + P + Q \leq m
   \]
5. For each set of \((p, q, P, Q)\), estimate the parameters for each model, that is,
   \[
   \emptyset_1, \emptyset_2, \ldots, \emptyset_p, \theta_1, \theta_2, \ldots, \theta_q, \Phi_1, \Phi_2, \ldots, \Phi_p
   \]
6. Compute the AIC for each model, and choose the one with smallest AIC.
7. After \((p, d, q, P, Q)\) is selected, we determine the seasonal differencing filter by selecting the smaller AIC between the model with \(D = 0\) and \(D = 1\).
8. Our final model will have identified the order of \((p, d, q, P, D, Q)\).

With the use of statistical software such are R.
Comparison of the Forecasting Models

Diagnostic checks help to determine if the anticipated model is adequate. At this stage, an examination of the residuals from the fitted model is done and if it fails the diagnostic tests, it is rejected and we repeat the cycle until an appropriate model is achieved. Different combinations of AR and MA individually yield different ARIMA models. The optimal model is obtained on the basis of minimum value of Akaike Information Criteria (AIC). The Root Mean Square Error (RMSE) and the Mean Absolute Percentage Error (MAPE) are used to evaluate the performance of the various models and are given below. For comparing the forecasting performance of competing models, the measure of accuracy of mean absolute percent error (MAPE) is calculated as:

\[
MAPE = \frac{1}{n} \sum_{t=1}^{n} \left| \frac{Y_t - F_t}{Y_t} \right| * 100
\]

(5-14)

Where \( y_t \) (t=1, 2 . . . n) is the actual value, and \( F(t= 1, 2, . . . , n) \) represents the forecasted value. The lower the value of MAPE is, the better the forecast will be. According to Lewis
(1982), the MAPE greater than 50% denotes inaccuracy of forecasting, 20–50% is reasonable, 10–20% is good, and smaller than 10% shows high accuracy of forecasting. Table 5-1 shows the forecast accuracy for both forecasting methods used.

Table 5.2: Residuals summary

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<tr>
<th>Forecast Accuracy</th>
<th>ME</th>
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<th>MAE</th>
<th>MPE</th>
<th>MAPE</th>
<th>ACF1</th>
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<td></td>
<td></td>
<td></td>
<td></td>
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<td>1031.201</td>
<td>797.2927</td>
<td>0.395793</td>
<td>4.433043</td>
<td>0.004798</td>
</tr>
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<td>2820.974</td>
<td>2381.718</td>
<td>9.85867</td>
<td>9.85867</td>
<td>0.360309</td>
</tr>
<tr>
<td><strong>Holt-Winters</strong></td>
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<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
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<td>0.309376</td>
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</table>

The Holt-Winter model outperforms the ARIMA model due to it lower MAPE. However since the ARIMA model MAPE is smaller than 20%, this indicates the forecasting performance is also good according to Lewis (1982).

Initially, we employed the Holt-Winters method with both additive and multiplicative seasonality to forecast tourists’ arrivals. Figure 5.4 shows the data alongside the within-sample one-step-ahead forecasts over the sample period 2000–2011 and the forecasts for the period 2012–2013. The data show an obvious seasonal pattern with peaks observed in the December of each year as this corresponds to the Belizean Tourist season. The results show that the method with the multiplicative seasonality fits the data best. This was expected as the time plot shows the seasonal variation in the data increases as the level of the series increases. This is also reflected in the two sets of forecasts; the forecasts generated by the method with multiplicative seasonality portray larger and increasing seasonal variation as the level of the forecasts increases compared to the forecasts generated by the method with additive seasonality. Because the nature of the
data, we utilized the multiplicative method for further forecasting. Figure 5.5 shows the graph of the estimated Holt Winter model and its two year ahead forecast.

The application of the method with multiplicative seasonality is presented in Table 5.2 and Figure. Table 5.2 summarized the two year period ahead forecast values with 80% and 90% confidence intervals for the predicted values and the actual tourist arrivals for the same period.

![Forecasts from Holt-Winters’ multiplicative method](image)

**Figure 5.5: Forecast from H-W multiplicative model**
Figure 5.6: Forecasts from Holt Winters model

Table 5.4 shows the actual tourists’ arrival and forecasted monthly tourists’ arrival in Belize for period 2000-2013 using both the exponential smoothing and the ARIMA models. The time plot in Figure 5.1 revealed that there was a seasonal increasing trend from year 2000 to 2008 with a decrease in 2009 and 2011. And a increasing trend thereafter. For smoothing the data, Holt-Winter exponential Smoothing was used. The Holt–Winters exponential smoothing model is estimated by using the computer application, R and the parameters of $\alpha$, $\beta$, and $\gamma$ were obtained by grid searching from 0 to 1. The model with parameter values is selected based on the smallest sum of squared errors and subsequently used to produce the forecasting. The mean Absolute Percentage error (4.78286) was the least for $\alpha=0.1887396$, $\beta=0.02201329$, $\gamma=0.522769$. 
The values of for $\alpha=0.1887396$ is relatively low, indicating that the estimate of the level at current time period is based upon both recent observations and some observation in the more distant past. The value of $\beta=0.02201329$ indicated that the estimate of the slope $b$ of trend component is updated over the time series, as the level change the slope $b$ of the trend component does not remain the same over the time series.

Following the ARIMA model procedure outline before, ARIMA model were fitted to the tourist arrival series. At the estimation stage, the autocorrelation (ACF) and partial autocorrelation (PACF) were checked to identify any autoregressive or moving average process.

### Table 5.3: H-W period ahead forecast values

<table>
<thead>
<tr>
<th>Month</th>
<th>Year</th>
<th>Holt - Winter</th>
<th>Lo 80</th>
<th>Hi 80</th>
<th>Lo 95</th>
<th>Hi 95</th>
<th>Actual Arrival</th>
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</thead>
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<td>Jan</td>
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<td>25997.72</td>
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<td>26483.69</td>
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<td>29427.813</td>
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<td>31952.97</td>
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</table>
Figure 5.7: Forecasts from Holt-Winter

Figure 5.8: Holt-Winter residual plot
Since the correlogram shows that one of the sample autocorrelations for lags 1-20 exceed the significance bounds, and the p-value for the Ljung-Box test is 0.7755, we can conclude that there is very little evidence for non-zero autocorrelations in the forecast errors up to lag 20 as shown in Figure 5-13. The spike in the plot suggests that the model can be slightly improved.
although it is unlikely to make much difference to the resulting forecast in Table 5-3. The
forecasted tourists’ arrival for the year 2012-2013 is presented in Table 5-3 along with the 80%
and 90% confidence interval. When compare with the actual observed arrivals it appears that the
model fits the data very well as seen in Figure 5-13.

The best fitted model was ARIMA(1,0,1)(2,1,1)(12). This can be written as

\[(1 - \theta_1 B)(1 - \Phi_1 B^{12} - \Phi_2 B^{24})(1 - B^{12})X_t = (1 + \theta_1 B)(1 + \Theta_1 B^{12})\varepsilon_t \] (5-15)

Substituting the estimated ARIMA coefficients,

\[(1 - 0.9744B)(1 + 0.0982B^{12} - 0.016B^{24})(1 - B^{12})X_t \]
\[= (1 - 0.7394B)(1 - 0.5240B^{12}) \] (5-16)

Simplifying it, we get

\[X_t - \varepsilon_t = 0.9744X_{t-1} + 0.9018X_{t-12} - 0.87871392X_{t-13} + 0.1088X_{t-24} - 0.10601472X_{t-25} - 0.0106X_{t-36} + 0.01032864X_{t-37} - 0.7394\varepsilon_t - 0.524\varepsilon_{t-12} + 038474\varepsilon_{t-13} \] (5-17)

The mathematical form of the one step ahead forecasting model for Belize is given by,

\[X_t = 0.9744X_{t-1} + 0.9018X_{t-12} - 0.87871392X_{t-13} + 0.1088X_{t-24} - 0.10601472X_{t-25} - 0.0106X_{t-36} + 0.01032864X_{t-37} - 0.7394\varepsilon_t - 0.524\varepsilon_{t-12} + 038474\varepsilon_{t-13} \] (5-18)

which is different from the model forecasted by United Nation in their 1992 report on Belize.
Table 5.4: ARIMA model Ahead Forecast Values

<table>
<thead>
<tr>
<th>Month</th>
<th>Year</th>
<th>Forecast</th>
<th>ARIMA Lo 80</th>
<th>Hi 80</th>
<th>Lo 95</th>
<th>Hi 95</th>
<th>Actual Arrival</th>
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<td>22065.93</td>
<td>31111</td>
<td>32423.60</td>
</tr>
</tbody>
</table>

Figure 5.11: Forecast from ARIMA(1.0,1)(2,1,1)12
Conclusion

Tourism in Belize and the Central America region underpin their fragile economies. With planning being an important aspect in tourism, the importance of forecasting cannot be overemphasized. Yet, little has been done on this issue. We have developed two models. The estimated models were subjected to validation process based on their statistical properties and forecasting capability. The ex post forecast shows that the ARIMA(1,0,1)(2,1,1)(12) scheme provides excellent short term forecast and the Holt-Winter also provides excellent forecasts. Of the two models however, based on MAPE and RMSE in Table 5-1 the results shows that the Holt-Winter Exponential smoothing model was the best for forecasting tourist arrival in Belize. The model does not show how various socioeconomic variables affect the number of arrivals. If such information is needed, a structural model should be developed and its simulation capability should be examined. Since the development of structural model can be costly, the benefit of additional information that would be obtained should be weighed against the costs of obtaining them.

The ARIMA models deal with seasonality in a more implicit manner--we can't easily see in the ARIMA output how the average for January, say, differs from the average for June. Depending on whether it is deemed important to isolate the seasonal pattern, this might be a factor in choosing among models. The ARIMA models have the advantage that, once they have been initialized, they have fewer "moving parts" than the exponential smoothing and adjustment models and as such they may be less likely to over fit the data. ARIMA models also have a more solid underlying theory with respect to the calculation of confidence intervals for longer-horizon forecasts than do the other models.
Chapter 6: Future Research

We proposed in developing a statistical economic model that drives the economy of Belize. This is extremely important because no such model does exist. The process, by which we will proceed in developing this model, is first identifying the attributable variables that drive the economy, such as agriculture, tourism, temperature and rainfall etc. with our model response variable which would be the value return base on the attributable variables. Most importantly, we will identify the interactions that would be involved in the modeling process and once we have identified it, we believe we can developed a very good model and validate it to be used by my country Belize.

Usefulness of such model is that it can estimate it potential economic behavior, secondly it identifies the significant attributable variables that drives the economy, thirdly it will identify the interaction of the risk variables that drives the economy, fourthly, we can use the modelling aspect to rank the attributable variables base on their percentage of contribution to the economy which is useful to government will know what entities they should focus in in order to increase the overall economy. Finally we will proceed perform surface response analysis that is we want to be within 95% certainly, what are the values of the attributable variables that drives the model that maximize the economy. This is extremely important because this information to the government in the sense that they can try to maintain the values that will maximize the economy. For example, if tourism is one of the key factors then they should aim to maintain the optimum values.

Belize has a significant need for developing a statistical model that drives the tourism sector. Since tourism is one on the key factors that drives the economy. In which our response variable will be tourism arrivals and the attributable variables mentioned in the previous
proposed research. Since we know from descriptive statistics, that tourism is one of the key factors in driving Belize’s economy. Having such a model is useful because we will able to identify the key factors that drive the tourism sectors.

As a result of the present study, we will continue the research on the subject area by studying the following problems. Investigate the selection of the best ARIMA model utilizing AIC versus BIC with respect to small, medium and large sample sizes. Overall, the results enable forecasters to choose the most suitable model, based on the available data, forecast horizon for forecasting tourism demand. A future research would aim at revisiting the robustness of our results in multivariate nonlinear frameworks, which controls for additional exogenous variables that affect tourism demand. Another area of interest is to examine whether a combination of forecasts based on the aforementioned models provides any additional gains in the forecasting accuracy of tourism demand in Belize.

While good research finding have been obtained, further work needs to be done to generalize the finding to other neighboring countries with similar characteristics. Future studies can employ the same forecasting model but with different data series for forecasting accuracy validity.
References


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